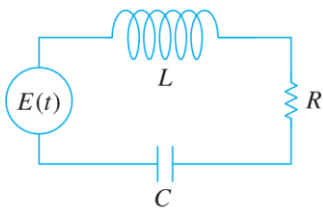


Fall 2019

微分方程 Differential Equations

Unit 01.3 DEs as Mathematical Models

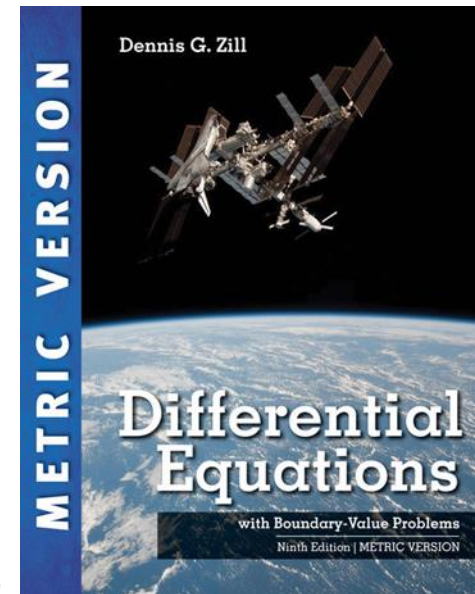


$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = E(t).$$

Feng-Li Lian

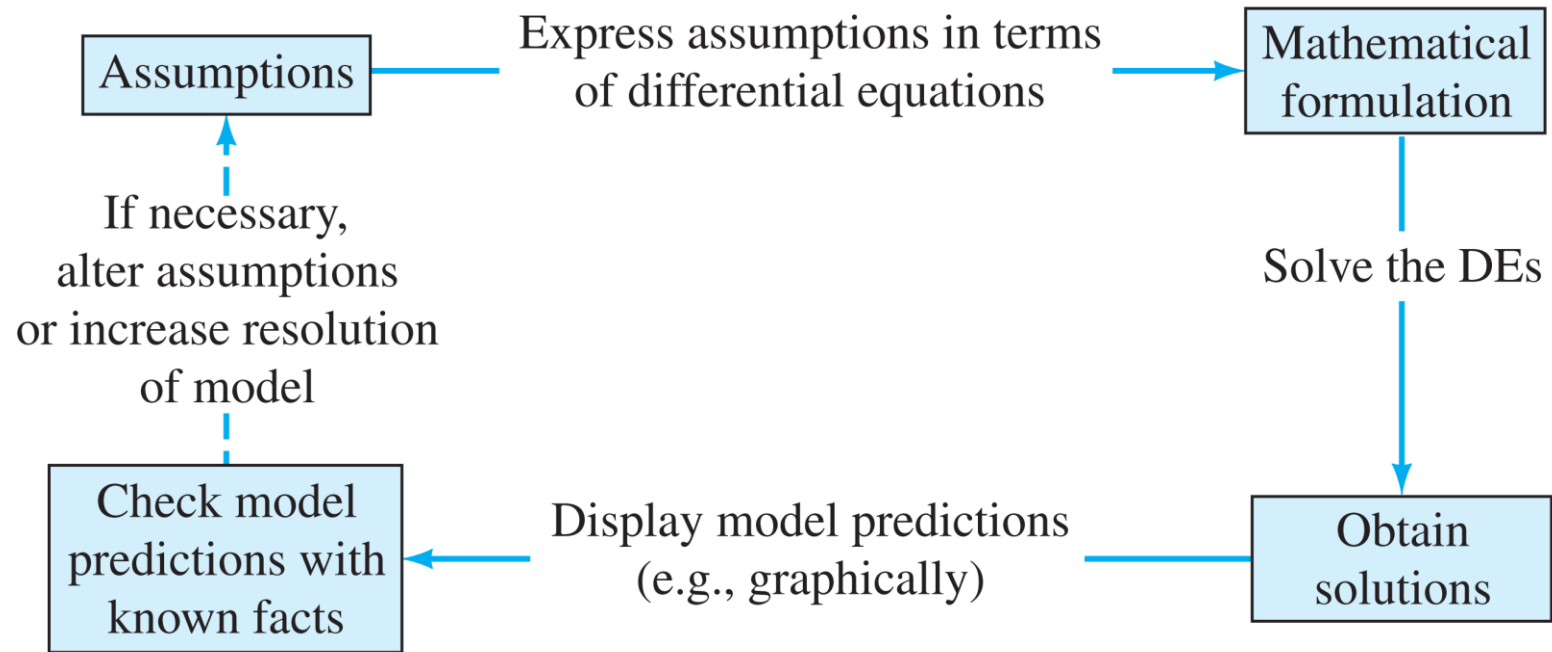
NTU-EE

Sep19 – Jan20



- The **mathematical description** of a **system** or a **phenomenon** is called a **mathematical model** and is constructed **with certain goals** in mind.
- **Construction** of a mathematical model of a system starts with:
 - Identify the **variables** for changing the system and specify the **level of resolution** of the model
 - Reasonable **assumptions**, or **hypotheses**, and **theorems** or **empirical laws**

■ Modeling process



■ Variables and Constants:

- $P(t)$: the total population at time t
- k : a constant of proportionality

■ Model:

$$\frac{dP}{dt} \propto P \quad \text{or} \quad \frac{dP}{dt} = k P \quad \text{--- (1)}$$

■ Variables and Constants:

- $A(t)$: the amount of the substance remaining at time t
- k : a constant of proportionality

■ Model:

$$\frac{dA}{dt} \propto A \quad \text{or} \quad \frac{dA}{dt} = k A \quad \text{--- (2)}$$

■ Note:

A single DE can serve as a mathematical model
for many different phenomena.

■ Variables and Constants:

- $T(t)$: the temperature of a body at time t
- T_m : the temperature of the surrounding medium
- k : a constant of proportionality

■ Model:

$$\frac{dT}{dt} \propto T - T_m \quad \text{or} \quad \frac{dT}{dt} = k(T - T_m) \quad \text{--- (3)}$$

■ Variables and Constants:

- $x(t)$: # of people who have contracted the disease
- $y(t)$: # of people who have not yet been exposed
- k : a constant of proportionality

■ Model:

$$\frac{dx}{dt} = k x y \quad \text{--- (4)}$$

$$\frac{dx}{dt} = k x (n + 1 - x) \quad \text{--- (5)}$$

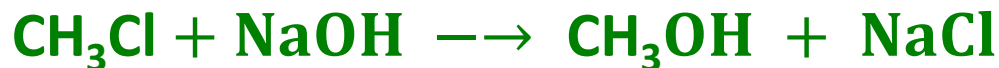
$$IF: x + y = n + 1$$

■ Variables and Constants:

- X : the amount of chemical C formed at time t
- α, β : the amounts of chemicals A and B at $t = 0$
(the initial amounts)
- k : a constant of proportionality

■ Model:

$$\frac{dX}{dt} = k (\alpha - X) (\beta - X) \quad \text{--- (6)}$$



■ Variables and Constants:

- $A(t)$: the salt in kilograms in the tank at time t
- R_{in} : input rate of salt in kilograms per minute
- R_{out} : output rate of salt
- Concentration of salt inflow/outflow
- Input/output rate of brine

■ Model:

$$\frac{dA}{dt} = R_{in} - R_{out} \quad \text{--- (7)}$$

$$\frac{dA}{dt} = 2.5 - \frac{A}{100} \quad \text{or} \quad \frac{dA}{dt} + \frac{1}{100} A = 2.5 \quad \text{--- (8)}$$

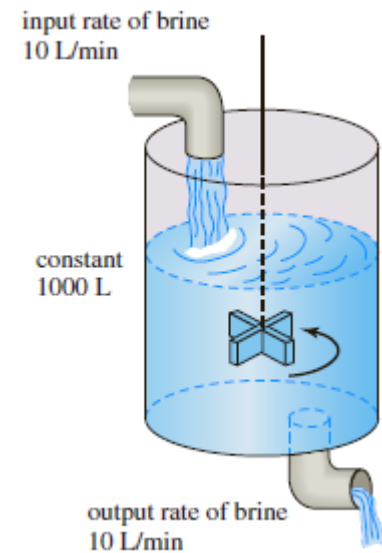
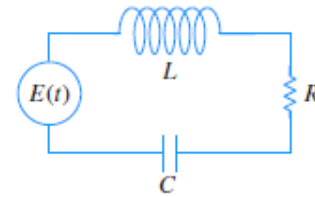


Figure 1.3.2: Mixing tank

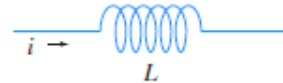
■ Variables and Constants:

- $i(t)$: The current in a circuit at time t
- $q(t)$: The charge on a capacitor at time t
- L, R, C : Inductance, resistance, and capacitance

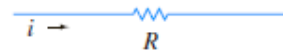


(a) LRC-series circuit

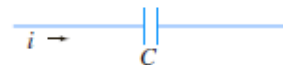
Inductor
inductance L : henry (H)
voltage drop across: $L \frac{di}{dt}$



Resistor
resistance R : ohm (Ω)
voltage drop across: iR



Capacitor
capacitance C : farad (F)
voltage drop across: $\frac{1}{C} q$



(b)

■ Model:

$$L \frac{di}{dt} = L \frac{d^2 q}{dt^2} \qquad iR = R \frac{dq}{dt} \qquad \frac{1}{C} q$$

$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = E(t)$$

--- (11)

■ Variables and Constants:

➤ $s(t)$: Position of rock relative to the ground at time t

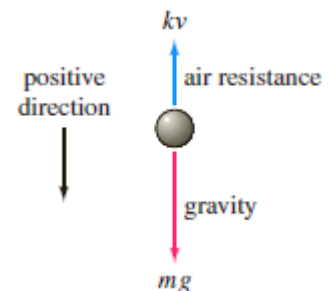
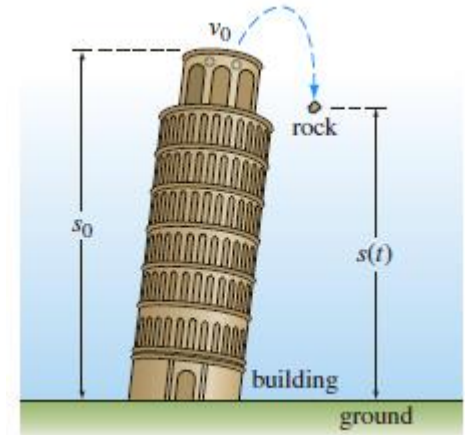
■ Model:

$$m \frac{d^2 s}{dt^2} = -mg \quad \text{or} \quad \frac{d^2 s}{dt^2} = -g \quad (12)$$

$$\frac{d^2 s}{dt^2} = -g, \quad s(0) = s_0, \quad s'(0) = v_0 \quad (13)$$

$$m \frac{dv}{dt} = mg - kv \quad (14)$$

$$m \frac{d^2 s}{dt^2} = mg - k \frac{ds}{dt} \quad \text{or} \quad m \frac{d^2 s}{dt^2} + k \frac{ds}{dt} = mg \quad (15)$$



■ Variables and Constants:

➤ $s(t)$: Position of rock relative to the ground at time t

■ Model:

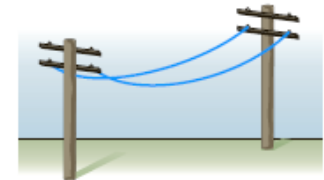
$$T_1 = T_2 \cos \theta \quad \text{and} \quad W = T_2 \sin \theta$$

$$\tan \theta = \frac{W}{T_1} \quad \text{and} \quad dy/dx = \tan \theta$$

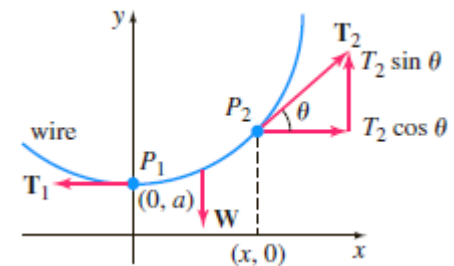
$$\frac{dy}{dx} = \frac{W}{T_1} \quad (16)$$



(a) suspension bridge cable



(b) telephone wires



- $\frac{dy}{dx} = f(x, y)$

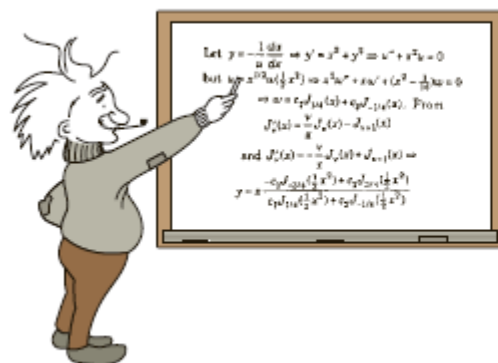
$$\Rightarrow y = \Phi(x) \quad y(x_0) = c_0$$

- $a_2(x) \frac{d^2 y(x)}{dx^2} + a_1(x) \frac{dy(x)}{dx} + a_0(x) y(x) = g(x)$

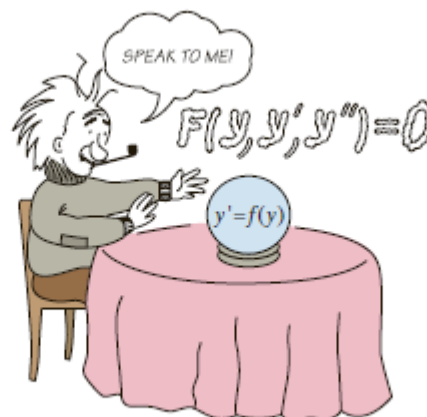
$$\Rightarrow y = \Phi(x) \quad \begin{cases} y(x_0) = p_0 \\ y'(x_0) = v_0 \end{cases}$$

$$\begin{cases} y(x_1) = c_1 \\ y(x_2) = c_2 \end{cases}$$

- Does the DE actually **have solutions**?
- If a solution of the DE **exists** and satisfies an **initial condition**, is it the **only** such solution?
- What are some of the **properties** of the unknown solutions?
- What can we say about the **geometry** of the solution curves?
- Can we somehow **approximate the values** of an unknown solution?



(a) analytical



(b) qualitative



(c) numerical

■ Midterm Exam

– 1-1, 1-2, 1-3

(Introduction)

– 2-1, 2-2, 2-3, 2-4, 2-5, 2-6

(First Order DE - Math)

– 3-1, 3-2, 3-3

(First Order DE - Modeling)

– 4-1, 4-2, 4-3, 4-4, 4-5

(Higher Order DE - Math)

■ Final Exam

– 4-6, 4-7

(Higher Order DE - Math)

– 5-1

(Higher Order DE - Modeling)

– 7-1, 7-2, 7-3, 7-4, 7-5, 7-6

(Transform – Laplace)

– 11-1, 11-2, 11-3

(Transform – Fourier)

– 12-1

(Partial DE)