

Scalable Exploration of Functional Dependency by Interpolation and Incremental SAT Solving

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Outline

- Introduction
- Prior work
- Our approach
- Experimental results
- Conclusions

Introduction

□ Functional dependency

- $f(x) = h(g_1(x), g_2(x), \dots, g_m(x)) = h(G(x))$

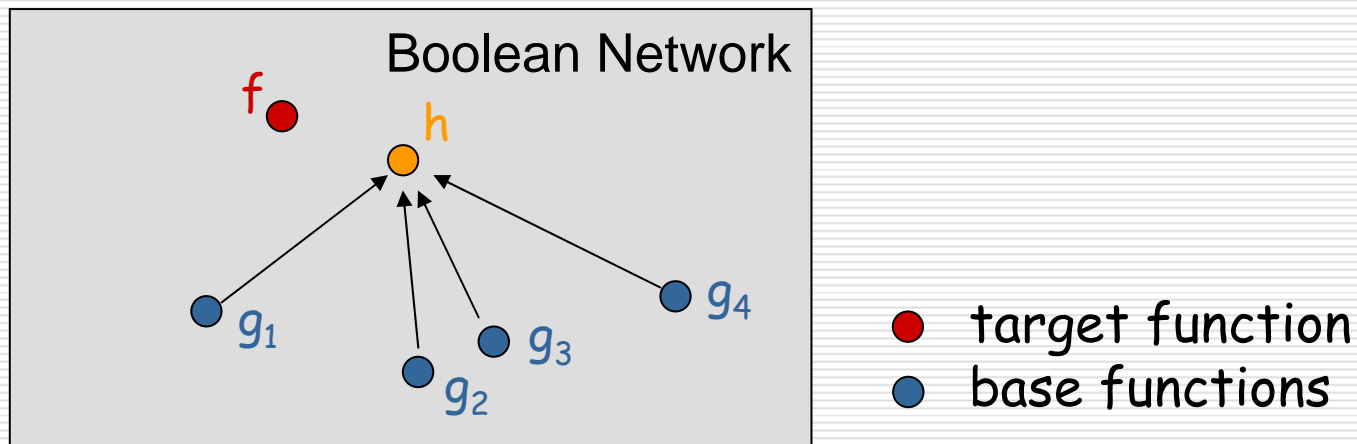
- Under what condition can a function f be expressed as some function h over a set of functions G ?

- h exists $\Leftrightarrow \nexists a, b$ such that $f(a) \neq f(b)$ and $G(a) = G(b)$

i.e., G is more distinguishing than f

Applications

- ❑ Resynthesis/rewiring [KK04]
- ❑ Redundant register removal [LN91,STB96]
- ❑ BDD minimization [HD93]
- ❑ Verification reduction [JB04]
- ❑ ...

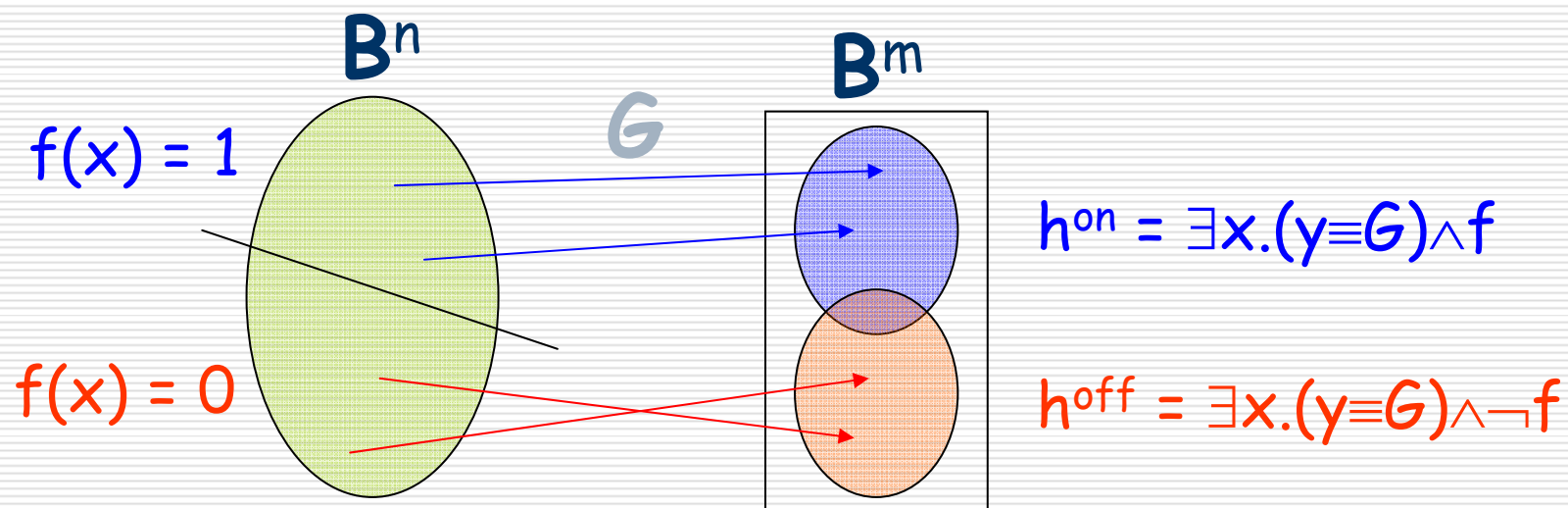


Prior Work

□ BDD-based computation of h

$$h^{\text{on}} = \{y \in \mathbf{B}^m : y = G(x) \text{ and } f(x) = 1, x \in \mathbf{B}^n\}$$

$$h^{\text{off}} = \{y \in \mathbf{B}^m : y = G(x) \text{ and } f(x) = 0, x \in \mathbf{B}^n\}$$



BDD-based Computation

- Not robust
 - 2 image computations for every choice of G
 - Inefficient when $|G|$ is large or when there are many choices of G

- Move on to SAT?

SAT-based Computation

□ h exists \Leftrightarrow

$\nexists a, b$ such that $f(a) \neq f(b)$ and $G(a) = G(b)$,
i.e., $(f(x) \neq f(x^*)) \wedge (G(x) = G(x^*))$ is **UNSAT**

□ But **how to derive h ?**

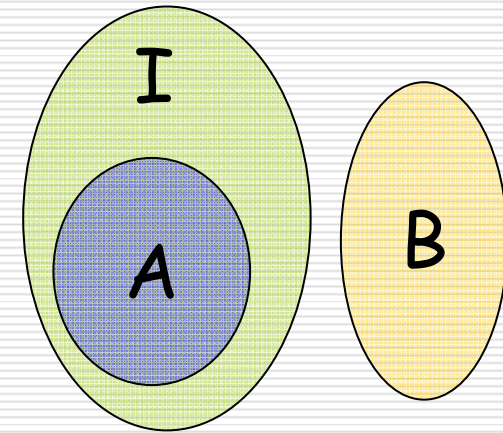
Moreover **how to select G ?**

Craig Interpolation

- $A \wedge B$ is UNSAT for clause sets A and B .

Then there exists an **interpolant** I of A such that

1. $A \Rightarrow I$
2. $I \wedge B$ is UNSAT
3. I refers only to the common variables of A and B

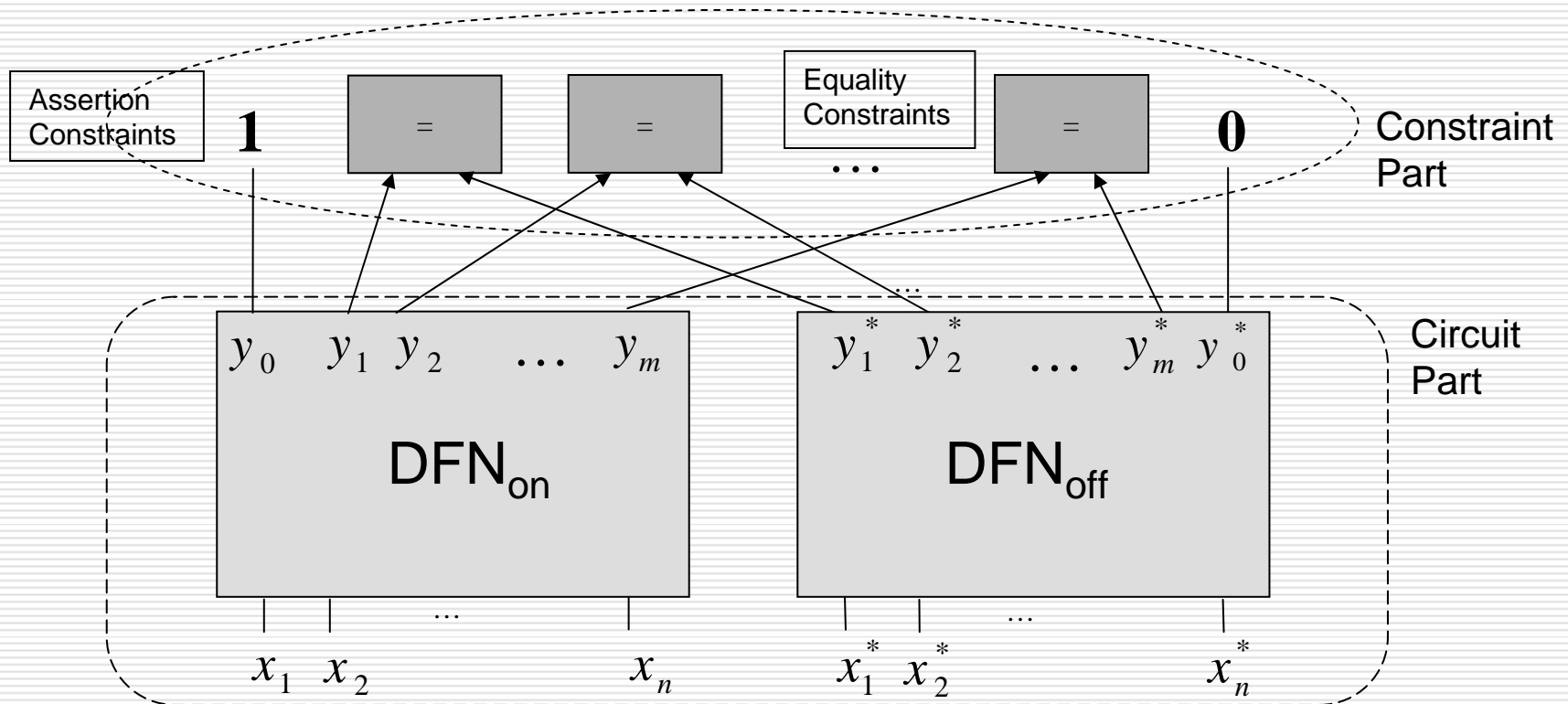


I is an abstraction of A

- Now what ?
Connecting I with h

The Magic

□ $(f(x) \neq f(x^*)) \wedge (G(x) \equiv G(x^*))$ is UNSAT



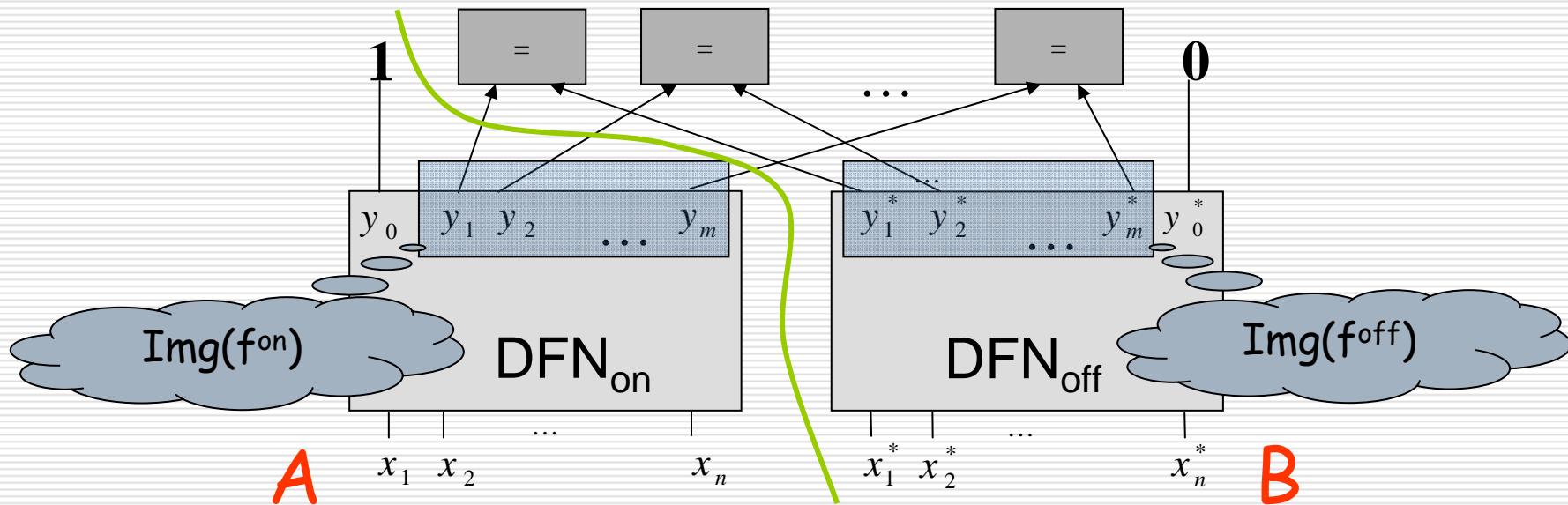
Premises

- Interpolant is of size linear to the refutation size
 - Resolution refutations of UNSAT CNF formulas can be generated from DPLL-style SAT solvers, and so can interpolants

- Circuit-to-CNF translation is doable in linear time
 - Intermediate variables are introduced

It Works!

- Clause set **A**: $C_{DFN_{on}}, Y_0$
- Clause set **B**: $C_{DFN_{off}}, \neg Y_0^*, (y_i \equiv y_i^*)$ for $i = 1, \dots, m$
- **I** is an overapproximation of $\text{Img}(f^{on})$ and is disjoint from $\text{Img}(f^{off})$
- **I** only refers to y_1, \dots, y_m
- Therefore, **I** corresponds to a feasible implementation of **h**



Incremental SAT Solving

□ Controlled equality constraints

$$(y_i \equiv y_i^*) \rightarrow (\neg y_i \vee y_i^* \vee \alpha_i) (y_i \vee \neg y_i^* \vee \alpha_i)$$

with auxiliary variables α_i

$\alpha_i = \text{true} \Rightarrow i^{\text{th}}$ equality constraint is disabled

- Fast switch between target and base functions by unit assumptions over control variables
- Fast enumeration of different base functions
- Share learned clauses

SAT vs. BDD

□ SAT

■ Pros

- Detect multiple choices of \mathcal{G} automatically
- Scalable to large $|\mathcal{G}|$
- Fast enumeration of different target functions f
- Fast enumeration of different base functions \mathcal{G}

■ Cons

- Single feasible implementation of h

□ BDD

■ Cons

- Detect one choice of \mathcal{G} at a time
- Limited to small $|\mathcal{G}|$
- Slow enumeration of different target functions f
- Slow enumeration of different base functions \mathcal{G}

■ Pros

- All possible implementations of h

Experimental Setup

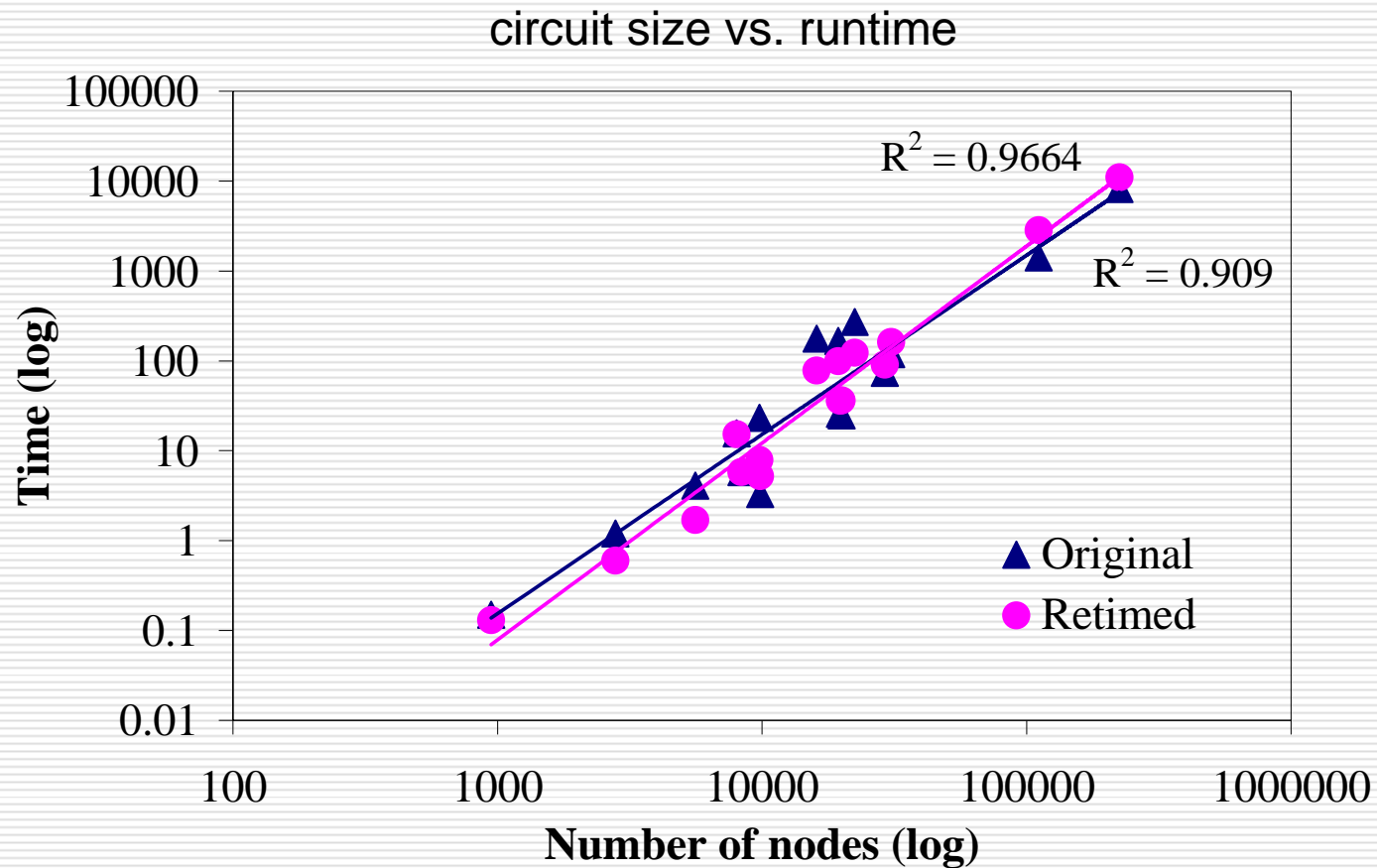
- Implemented in ABC using MiniSAT
- Detect functional dependency among transition functions of sequential circuits

Experimental Results

SAT vs. BDD

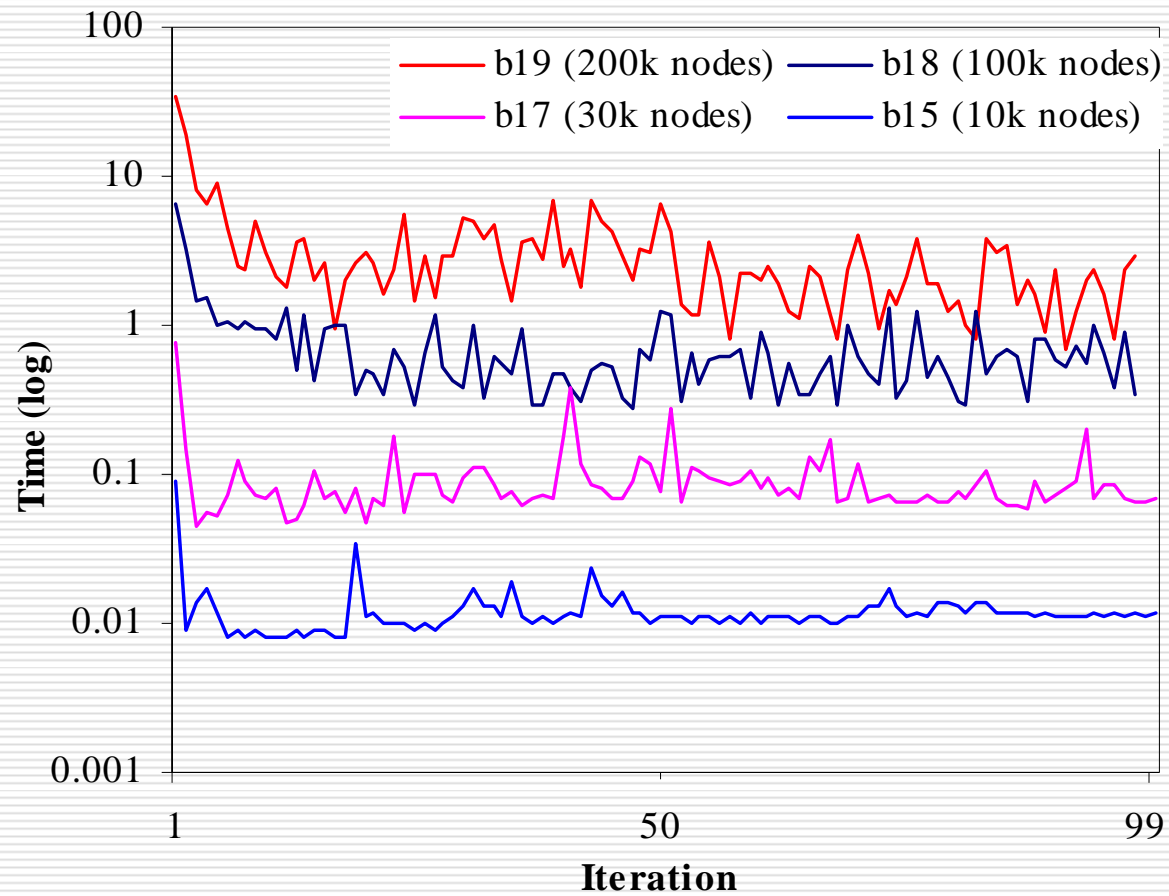
Circuit	#Nodes	Original			Retimed			SAT (original)		BDD (original)		SAT (retimed)		BDD (retimed)	
		#FF.	#Dep-S	#Dep-B	#FF.	#Dep-S	#Dep-B	Time	Mem	Time	Mem	Time	Mem	Time	Mem
s5378	2794	179	52	25	398	283	173	1.2	18	1.6	20	0.6	18	7	51
s9234.1	5597	211	46	x	459	301	201	4.1	19	x	x	1.7	19	194.6	149
s13207.1	8022	638	190	136	1930	802	x	15.6	22	31.4	78	15.3	22	x	x
s15850.1	9785	534	18	9	907	402	x	23.3	22	82.6	94	7.9	22	x	x
s35932	16065	1728	0	--	2026	1170	--	176.7	27	1117	164	78.1	27	--	--
s38417	22397	1636	95	--	5016	243	--	270.3	30	--	--	123.1	32	--	--
s38584	19407	1452	24	--	4350	2569	--	166.5	21	--	--	99.4	30	1117	164
b12	946	121	4	2	170	66	33	0.15	17	12.8	38	0.13	17	2.5	42
b14	9847	245	2	--	245	2	--	3.3	22	--	--	5.2	22	--	--
b15	8367	449	0	--	1134	793	--	5.8	22	--	--	5.8	22	--	--
b17	30777	1415	0	--	3967	2350	--	119.1	28	--	--	161.7	42	--	--
b18	111241	3320	5	--	9254	5723	--	1414	100	--	--	2842.6	100	--	--
b19	224624	6642	0	--	7164	337	--	8184.8	217	--	--	11040.6	234	--	--
b20	19682	490	4	--	1604	1167	--	25.7	28	--	--	36	30	--	--
b21	20027	490	4	--	1950	1434	--	24.6	29	--	--	36.3	31	--	--
b22	29162	735	6	--	3013	2217	--	73.4	36	--	--	90.6	37	--	--

Experimental Results (cont'd)



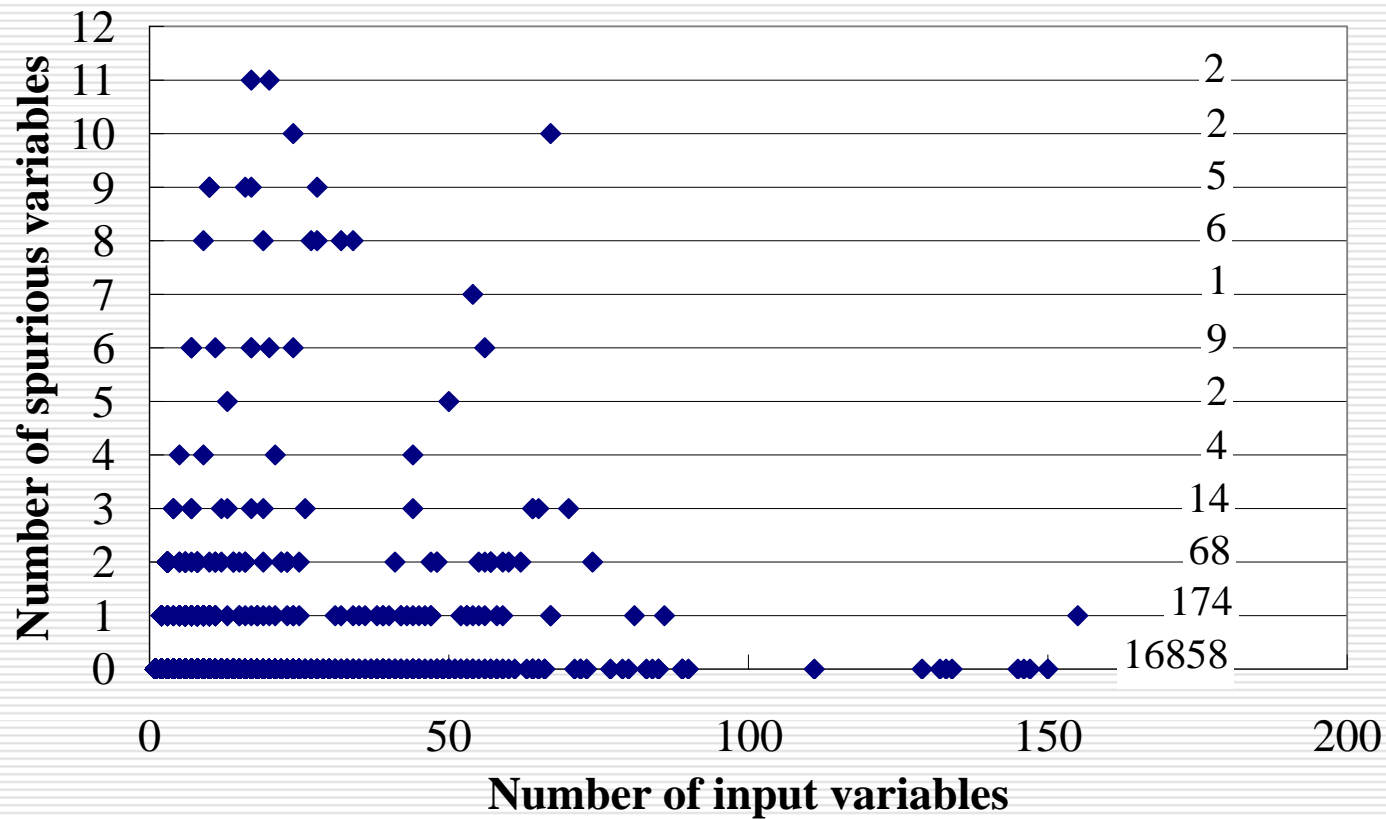
Experimental Results (cont'd)

Incremental SAT

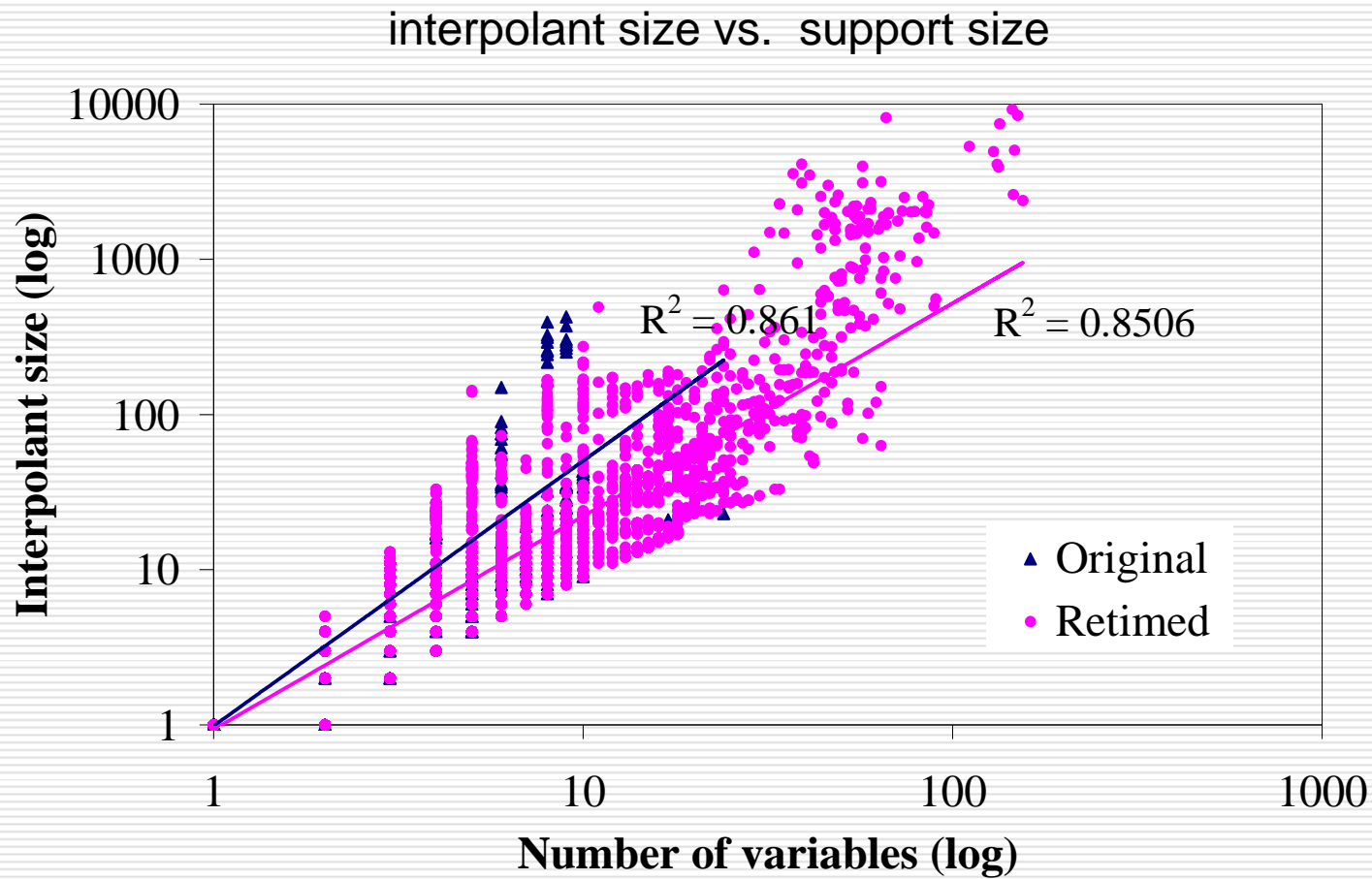


Experimental Results (cont'd)

#total input vs. #redundant inputs



Experimental Results (cont'd)



Conclusions and Future Work

□ Have shown

- Functional dependency is computable with pure SAT-solving and is scalable to large designs

□ To try

- Don't-care generation for h
- Other applications of Craig interpolation
- Hybrid approach combining BDD and SAT

Thank You
