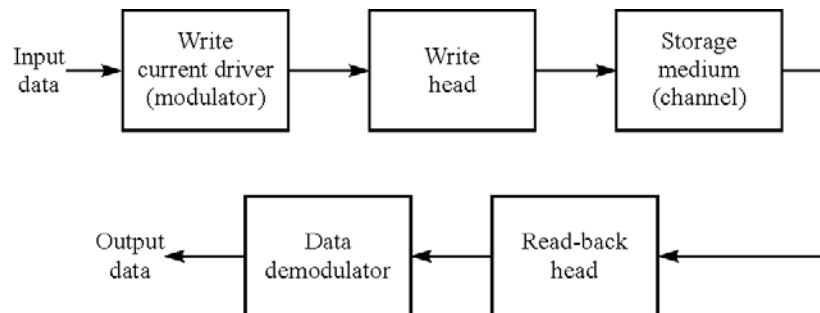


The Magnetic Recording Channels

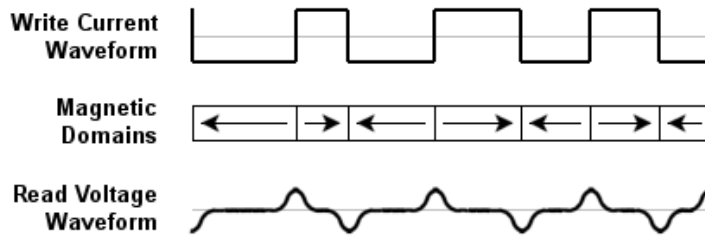
Partial Response Maximum Likelihood

Magnetic Storage Read/Write System

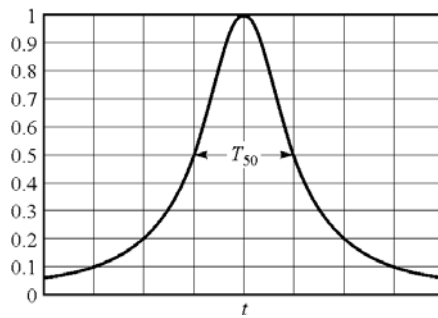


Magnetic Recording Channel (MRC)

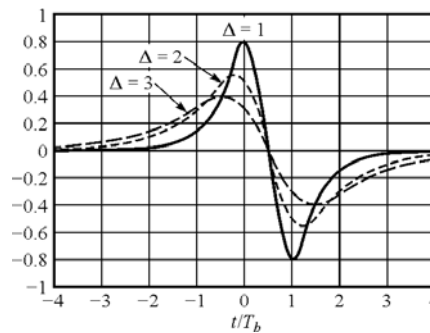
- Flux reversal instead of the absolute field
 - Easy to Measure
 - Easy Synchronization
 - Field Separation



Read Waveform/Readback pulse

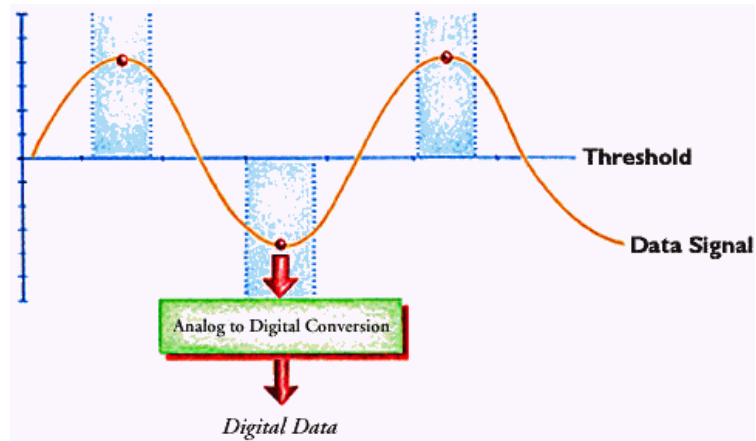


$$g(t) = \frac{1}{1 + (2t/T_{50})^2}$$



$$\Delta = T_{50}/T_b$$

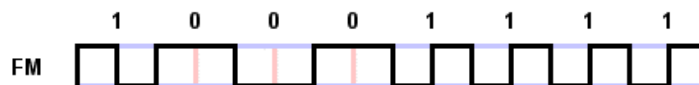
Traditional Peak Detection



Frequency Modulation

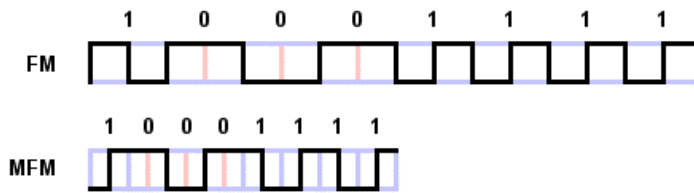
| Input Data Bits | Output coded Sequence | # of 1's | Prob. (%) |
|-----------------|-----------------------|----------|-----------|
| 0 | 10 | 1 | 50 |
| 1 | 11 | 2 | 50 |
| Weight | | 1.5 | 100 |

- 1: Reverse the flux
- 0: Don't reverse the flux



Modified Frequency Modulation (MFM) Miller code

| Input Data Bits | Output coded Sequence | # of 1's | Prob. (%) |
|-------------------|-----------------------|----------|-----------|
| 0 (preceded by 0) | 10 | 1 | 25 |
| 0 (preceded by 1) | 00 | 0 | 25 |
| 1 | 01 | 1 | 50 |
| Weight | | 0.75 | 100 |



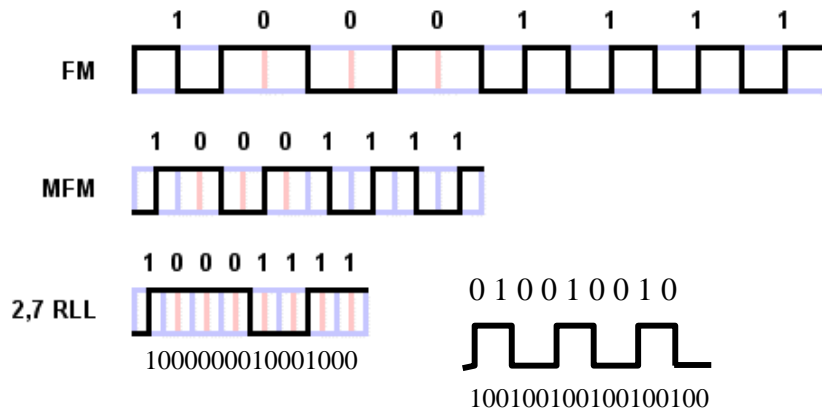
Run-Length Limit (d, κ)

RLL (2, 7)

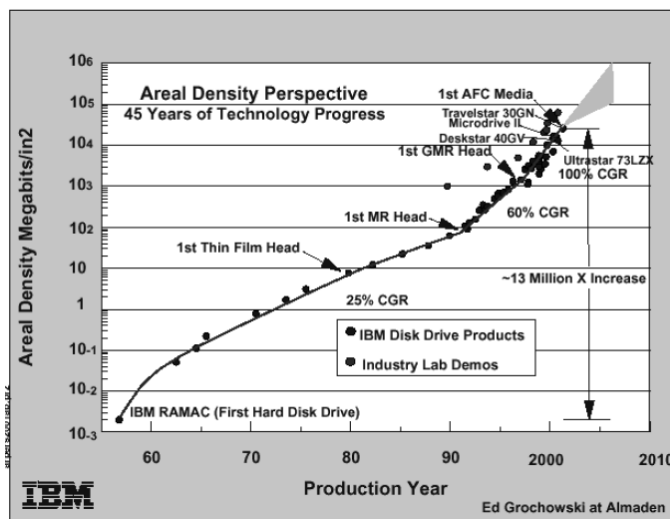
| Input Data Bits | Output coded Sequence | # of 1's | Prob. (%) |
|-----------------|-----------------------|----------|-----------|
| 11 | 1000 | 1/2 | 25 |
| 10 | 0100 | 1/2 | 25 |
| 011 | 001000 | 1/3 | 12.5 |
| 010 | 100100 | 2/3 | 12.5 |
| 000 | 000100 | 1/3 | 12.5 |
| 0010 | 00100100 | 2/4 | 6.25 |
| 0011 | 00001000 | 1/4 | 6.25 |
| Weight | | 0.4635 | 100 |

(Small difference with the textbook)

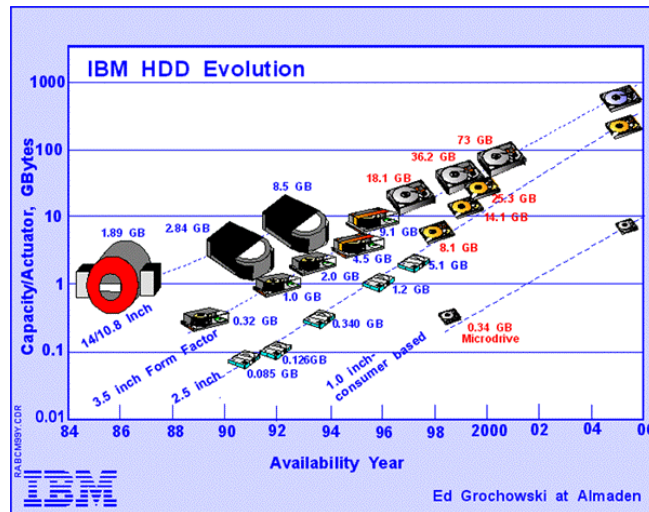
RLL (2, 7)



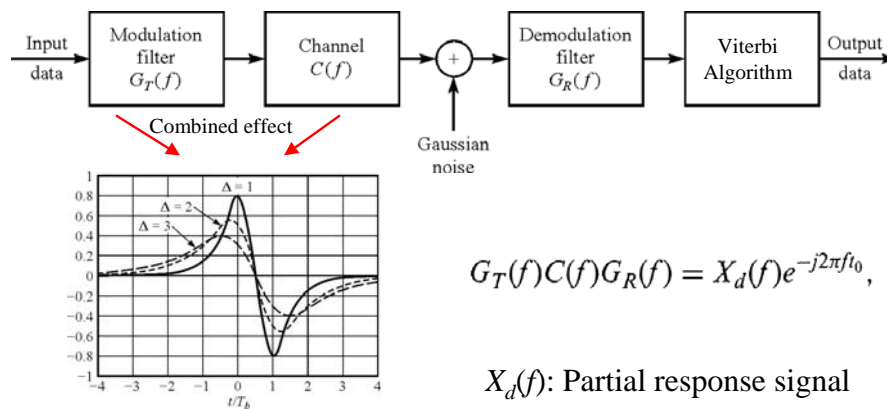
Storage Density vs. time



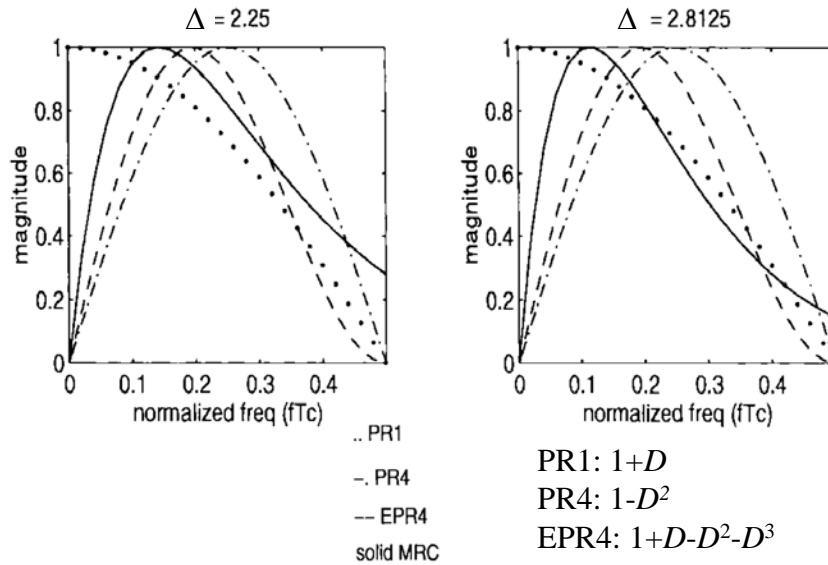
Hard Disk Evolution



Partial Response Maximum Likelihood



Partial Response vs. MRC



Maximum Likelihood Sequence Detection

- pdf of received signal

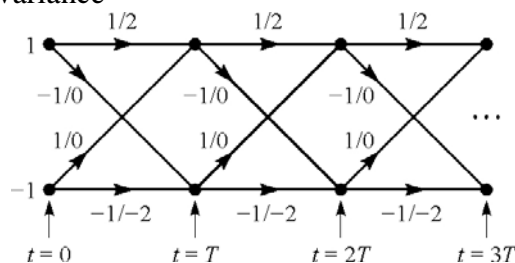
$$f(\mathbf{y}_N | \mathbf{I}_N) = \frac{1}{(2\pi \det \mathbf{C})^{N/2}} \exp\left[-\frac{1}{2}(\mathbf{y}_N - \mathbf{B}_N)' \mathbf{C}^{-1}(\mathbf{y}_N - \mathbf{B}_N)\right]$$

\mathbf{y}_N : received sequence

\mathbf{B}_N : transmitted sequence

\mathbf{I}_N : bit (or PAM) sequence

\mathbf{C} : Noise covariance



PRML (duobinary PR1 signal)

- Metric

$$\hat{\mathbf{I}}_N = \arg \min_{\mathbf{I}_N} [(\mathbf{y}_N - \mathbf{B}_N)' \mathbf{C}^{-1} (\mathbf{y}_N - \mathbf{B}_N)]$$

Ignore noise correlation:

$$\begin{aligned} \hat{\mathbf{I}}_N &= \arg \min_{\mathbf{I}_N} [(\mathbf{y}_N - \mathbf{B}_N)' (\mathbf{y}_N - \mathbf{B}_N)] \\ &= \arg \min_{\mathbf{I}_N} \left[\sum_{m=1}^N \left(y_m - \sum_{k=0}^L x_k I_{m-k} \right)^2 \right] \end{aligned} \quad B_m = \sum_{k=0}^L x_k I_{m-k}$$

- Viterbi Algorithm

$$DM_m(\mathbf{I}_m) = DM_{m-1}(\mathbf{I}_{m-1}) + \left(y_m - \sum_{k=0}^L x_k I_{m-k} \right)^2$$

PRML (PR4 signal)

Modified duobinary (homework)

- PR4: $1-D^2$