

Chapter 11 Frequency response and filter

11.1 Frequency response

amplitude ratio, phase shift, frequency-response curve

11.2 Filters

lowpass filter, highpass filter, bandpass filter, notch filter

11.3 Op-amp filter circuits (optional)

11.4 Bode plots

decibel, highpass function, lowpass function, quadratic function

11.5 Frequency-response design (optional)

11.6 Butterworth filters (optional)

Butterworth polynomial, lowpass filter, highpass filter

11.1 Frequency response

Basics

1. Complex-frequency waveform representation of a real signal

$$\begin{aligned} x(t) &= X_m e^{\sigma t} \cos(\omega t + \phi_x) \\ &= \operatorname{Re}[X_m e^{j\phi_x} e^{(\sigma + j\omega)t}] \\ &= \operatorname{Re}[\underline{X} e^{st}], \underline{X} = X_m e^{j\phi_x} \end{aligned} \quad \longrightarrow \quad \boxed{H(s) = \frac{\underline{Y}}{\underline{X}}, \quad s = \sigma + j\omega} \quad \longrightarrow \quad \begin{aligned} x(t) &= X_m \cos(\omega t + \phi_x) \\ &= \operatorname{Re}[X_m e^{j\phi_x} e^{j\omega t}] \\ &= \operatorname{Re}[\underline{X} e^{j\omega t}] \end{aligned}$$

2. $\sigma = 0$, complex-frequency waveform $\rightarrow$ sinusoidal ac waveform

$$\begin{aligned} x(t) &= X_m \cos(\omega t + \phi_x) \\ &= \operatorname{Re}[X_m e^{j\phi_x} e^{j\omega t}] \\ &= \operatorname{Re}[\underline{X} e^{j\omega t}] \end{aligned} \quad \longrightarrow \quad \boxed{H(j\omega) = \frac{\underline{Y}}{\underline{X}}} \quad \longrightarrow \quad \begin{aligned} y(t) &= Y_m \cos(\omega t + \phi_y) \\ &= \operatorname{Re}[Y_m e^{j\phi_y} e^{j\omega t}] \\ &= \operatorname{Re}[\underline{Y} e^{j\omega t}] \end{aligned}$$

$$a(\omega) \equiv |H(j\omega)| = \frac{Y_m}{X_m} : \text{amplituderatio}, \theta(\omega) \equiv \angle H(j\omega) = \phi_y - \phi_x : \text{phaseshift}$$

3. Frequency-response curves: plots of $a(w)$ and $\theta(w)$

$$H(jw) = K \frac{(jw - z_1)(jw - z_2)\dots}{(jw - p_1)(jw - p_2)\dots}$$

$$a(w) = |K| \frac{|jw - z_1| |jw - z_2| \dots}{|jw - p_1| |jw - p_2| \dots}$$

$$\theta(w) \equiv \angle K + [\angle(jw - z_1) + \angle(jw - z_2) + \dots] - [\angle(jw - p_1) + \angle(jw - p_2) + \dots]$$

$$4. w \rightarrow \infty \quad a(w) \rightarrow \begin{cases} |K|, m = n \\ 0, m < n \end{cases}, \theta(w) \rightarrow \angle K + (m - n) \times 90^\circ$$

5. $w \rightarrow 0$, $a(w)$ and $\theta(w)$ depend on zeros and poles

Discussion

1. Ex. 11.1 $L=0.2\text{H}$, $R=8\Omega$ find steady-state response $v_{out}(t)$

$$v_{in}(t) = 10 \cos 20t + 10 \cos 300t$$

$$\underline{V}_{out} = \underline{V}_{in} \frac{R}{sL + R} = \underline{V}_{in} \frac{R/L}{s + R/L}$$

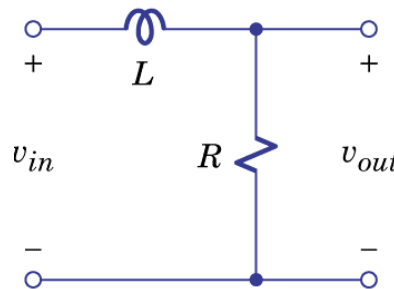
$$H(j\omega) = \frac{\underline{V}_{out}}{\underline{V}_{in}} = \frac{40}{j\omega + 40}$$

$$a(\omega) = |H(j\omega)| = \frac{40}{\sqrt{\omega^2 + 1600}}, \theta(\omega) = \angle H(j\omega) = -\tan^{-1} \frac{\omega}{40}$$

$$a(20) = 0.894, \theta(20) = -26.6^\circ, a(300) = 0.132, \theta(300) = -82.4^\circ$$

$$\underline{V}_{out} = \begin{cases} 10 \times H(20), & \text{for } \omega = 20 \\ 10 \times H(300), & \text{for } \omega = 300 \end{cases}$$

$$v_{out}(t) = 8.94 \cos(20t - 26.6^\circ) + 1.32 \cos(300t - 82.4^\circ)$$



frequency selective
response, lowpass filter

Frequency response approach is much easier than time-domain approach or phasor approach.

2. Ex.11.2 all-pass circuit

$$\begin{aligned}\underline{V}_{out} &= \underline{V}_C - \underline{V}_x \\ &= \underline{V}_{in} \left(\frac{1/sC}{R + 1/sC} - \frac{R_x}{2R_x} \right)\end{aligned}$$

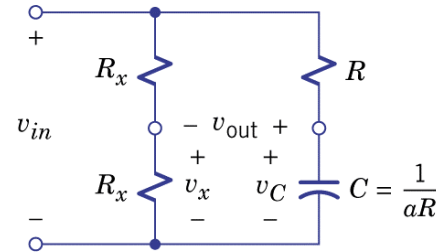
$$= \underline{V}_{in} \left(\frac{1}{sRC + 1} - \frac{1}{2} \right)$$

$$= \underline{V}_{in} \left(-\frac{1}{2} \right) \frac{sRC - 1}{sRC + 1}$$

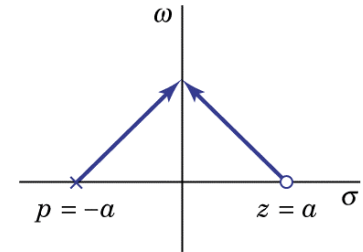
$$\rightarrow H(j\omega) = \frac{\underline{V}_{out}}{\underline{V}_{in}} = -\frac{1}{2} \frac{j\omega - 1/RC}{j\omega + 1/RC}$$

$$a(\omega) = -\frac{1}{2}$$

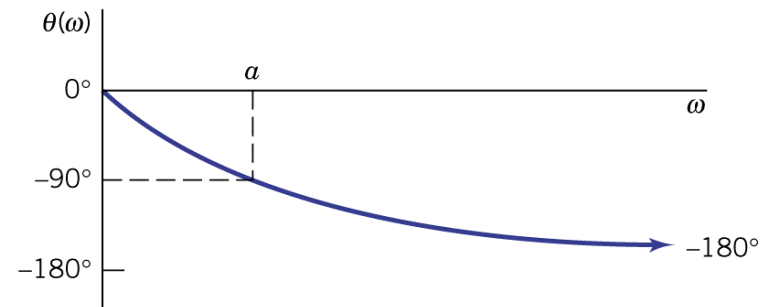
$$\theta(\omega) = \tan^{-1} \frac{-\omega}{1/RC} - \tan^{-1} \frac{\omega}{1/RC} = -2 \tan^{-1} \frac{\omega}{1/RC}$$



(a) All-pass network



(b) Pole-zero pattern

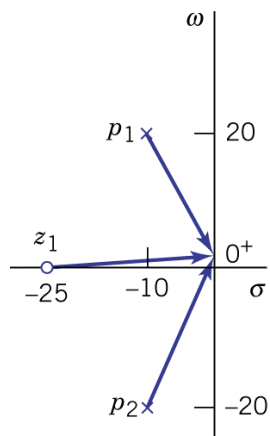
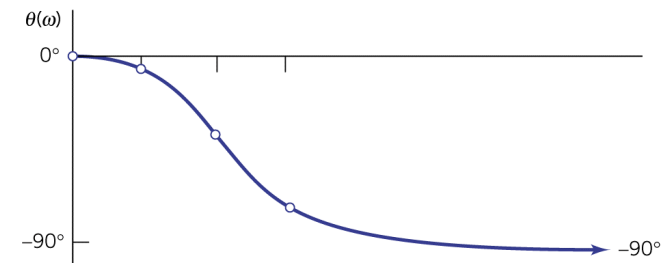
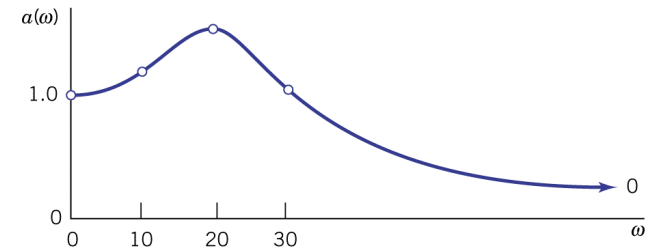


(c) Phase shift versus ω

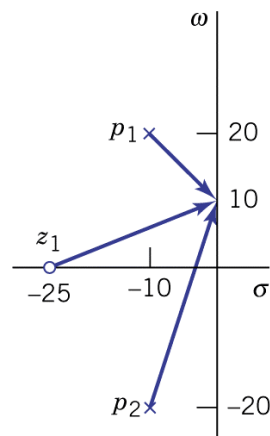
3. Ex. 11.3 plot frequency response

$$H(s) = \frac{20(s+25)}{s^2 + 20s + 500} = \frac{20[s - (-25)]}{(s - p_1)(s - p_2)}$$

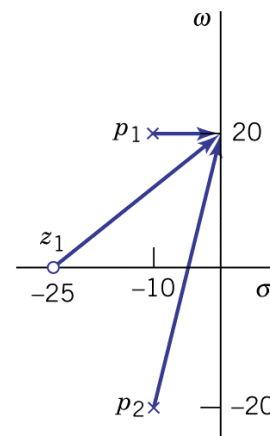
$$p_1, p_2 = -10 \pm j20$$



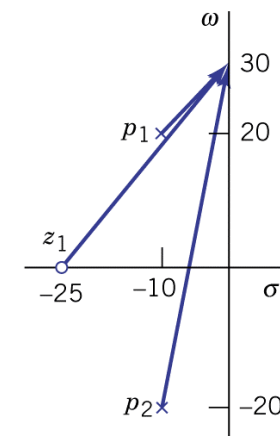
(a)



(b)



(c)

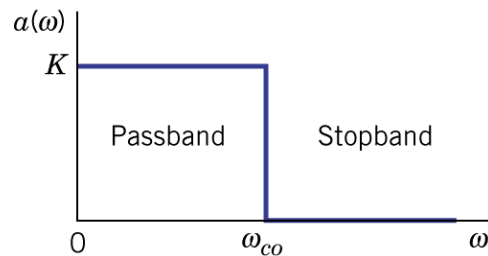


(d)

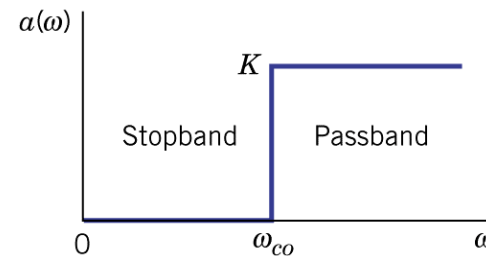
11.2 Filters

Basics

1. Ideal lowpass (LPF) and highpass (HPF) filters, ω_{co} : cutoff frequency

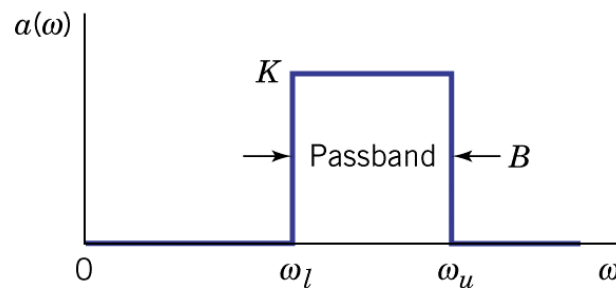


(a) Ideal lowpass filter

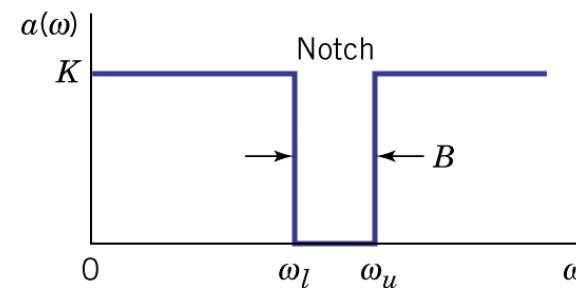


(b) Ideal highpass filter

2. Ideal bandpass (BPF) and notch (BSF) filters: ω_l : lower cutoff frequency, ω_u : upper cutoff frequency, $B = \omega_u - \omega_l$: bandwidth



(a) Ideal bandpass filter



(b) Ideal notch filter

Discussion

1. First-order LPF

$$H_{lp,1}(s) = \frac{V_{out}}{V_{in}} = \frac{1/sC}{R + 1/sC} = \frac{1/RC}{s + 1/RC}$$

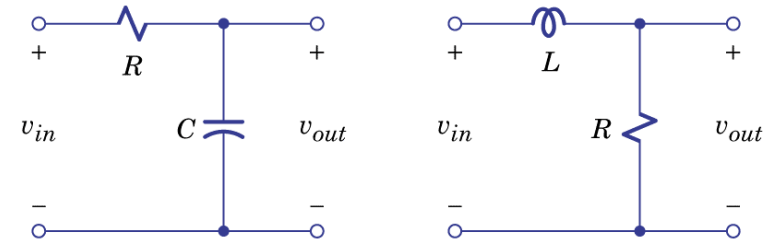
$$H_{lp,2}(s) = \frac{V_{out}}{V_{in}} = \frac{R}{sL + R} = \frac{R/L}{s + R/L}$$

$$H_{lp}(s) = \frac{K\omega_{co}}{s + \omega_{co}}, K = 1, \omega_{co} = \frac{1}{\tau}, \tau = RC$$

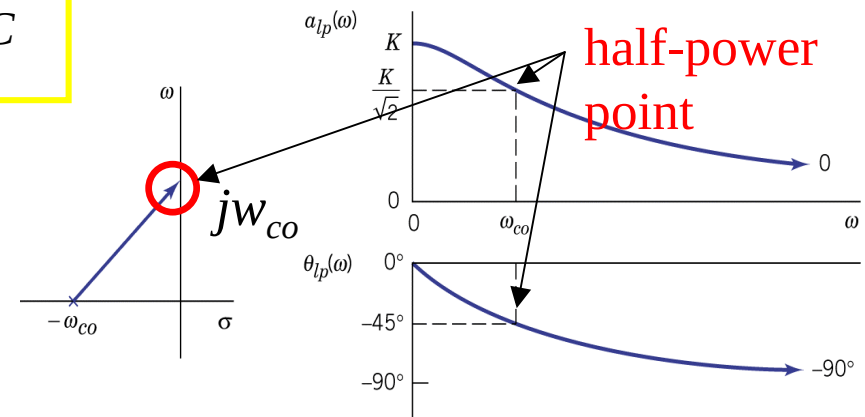
$$H_{lp}(j\omega) = \frac{K\omega_{co}}{j\omega + \omega_{co}} = \frac{K}{1 + j\frac{\omega}{\omega_{co}}}$$

$$a_{lp}(\omega) = \frac{K}{\sqrt{1 + (\omega/\omega_{co})^2}}$$

$$\theta_{lp}(\omega) = -\tan^{-1} \frac{\omega}{\omega_{co}}$$



(a) Lowpass filters



(a) s-plane diagram

(b) Frequency response curves

2. First-order highpass filter

$$H_{hp,1}(s) = \frac{V_{out}}{V_{in}} = \frac{R}{R + 1/sC} = \frac{s}{s + 1/RC}$$

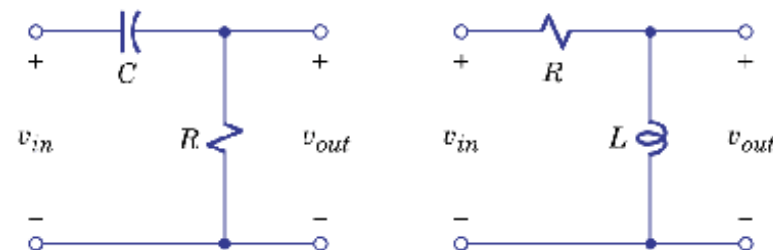
$$H_{hp,2}(s) = \frac{V_{out}}{V_{in}} = \frac{sL}{sL + R} = \frac{s}{s + R/L}$$

$$H_{hp}(s) = \frac{Ks}{s + \omega_{co}}, K = 1, \omega_{co} = \frac{1}{\tau}, \tau = \frac{L}{R}$$

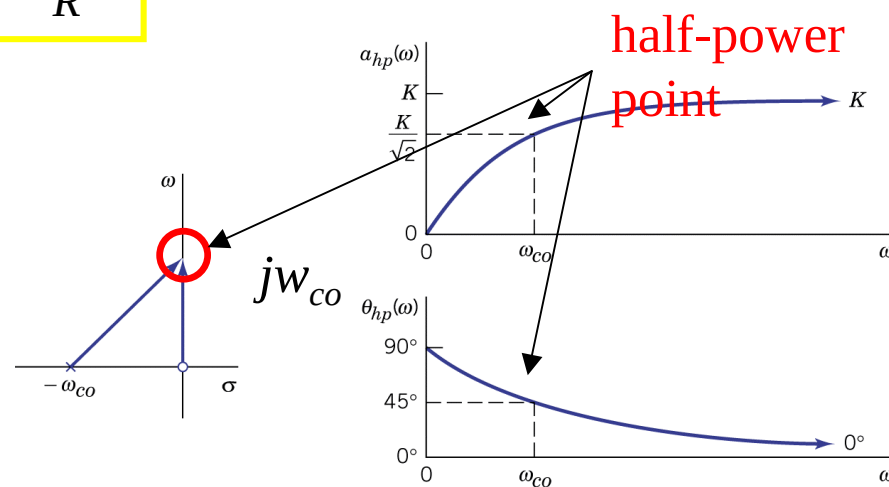
$$H_{hp}(j\omega) = \frac{Kj\omega}{j\omega + \omega_{co}} = \frac{K}{1 - j \frac{\omega_{co}}{\omega}}$$

$$a_{hp}(\omega) = \frac{K}{\sqrt{1 + (\omega_{co} / \omega)^2}}$$

$$\theta_{hp}(\omega) = \tan^{-1} \frac{\omega_{co}}{\omega}$$



(b) Highpass filters



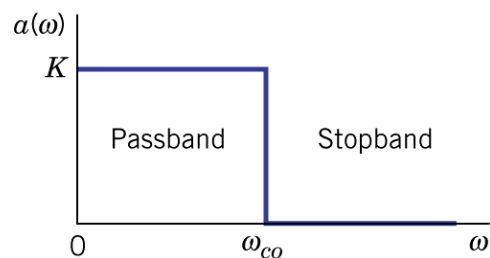
(a) s-plane diagram

(b) Frequency response curves

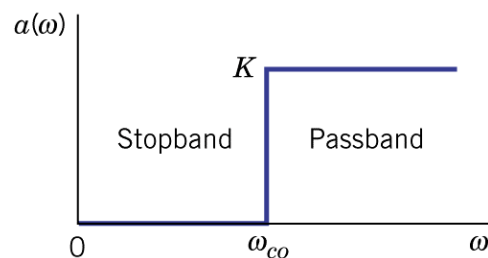
3. LPF to HPF transformation

$$H_{lp}(s) = \frac{Kw_{co}}{s + w_{co}}, H_{hp}(s) = \frac{Ks}{s + w_{co}}$$

$$s \rightarrow \frac{w_{co}^2}{s} \Rightarrow LPF \rightarrow HPF, H_{lp}\left(\frac{w_{co}^2}{s}\right) = \frac{Kw_{co}}{\frac{w_{co}^2}{s} + w_{co}} = \frac{Ks}{s + w_{co}} = H_{hp}(s)$$



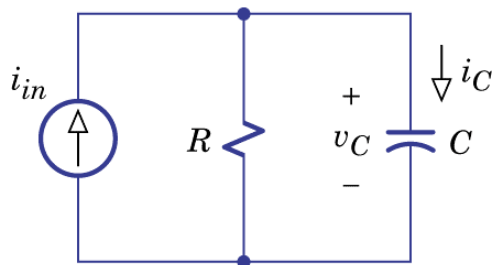
(a) Ideal lowpass filter



(b) Ideal highpass filter

$$0 \rightarrow \infty, w_{co} \rightarrow w_{co}$$

4. Ex.11.4 find $H(j\omega)$



$$\underline{I}_C = \underline{I}_{in} \frac{R}{R + 1/sC}$$

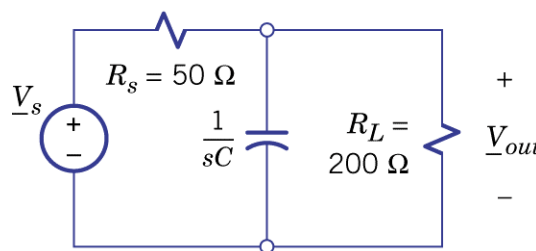
$$H(s) = \frac{\underline{I}_C}{\underline{I}_{in}} = \frac{R}{R + 1/sC} = \frac{s}{s + 1/RC}$$

$$H(j\omega) = \frac{j\omega}{j\omega + 1/RC} = \frac{1}{1 - j\frac{\omega_{co}}{\omega}}, \omega_{co} = \frac{1}{RC}, \text{HPF}$$

5. Ex.11.5 find $H(j\omega)$ to have $f_{co} \sim 4\text{kHz}$

Amplifier

Loudspeaker



$$\underline{V}_{out} = \underline{V}_s \frac{\frac{G_L + sC}{1} + \frac{1}{1}}{\frac{1}{G_s} + \frac{1}{G_L + sC}} = \underline{V}_s \frac{G_s}{G_s + G_L + sC}$$

$$H(s) = \frac{\underline{V}_{out}}{\underline{V}_s} = \frac{G_s}{G_s + G_L + sC} = \frac{G_s / C}{s + (G_s + G_L) / C} = \frac{K\omega_{co}}{s + \omega_{co}},$$

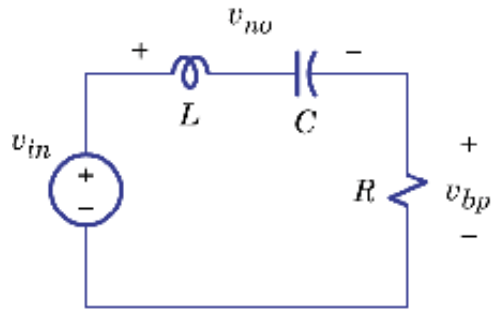
$$\omega_{co} = 2\pi f_{co} = \frac{G_s + G_L}{C} = \frac{1}{40C} \rightarrow C \approx 1\mu\text{F}, K = \frac{G_s}{G_s + G_L} = 0.8$$

$$\text{if } v_s = 5 \cos \omega_1 t + 0.5 \cos \omega_2 t, f_1 = 3\text{kHz}, f_2 = 16\text{kHz}$$

$$H(j\omega_1) = 0.64 \angle -37^\circ, H(j\omega_2) = 0.19 \angle -76^\circ$$

$$\rightarrow v_s = 3.2 \cos(\omega_1 t - 37^\circ) + 0.095 \cos(\omega_2 t - 76^\circ)$$

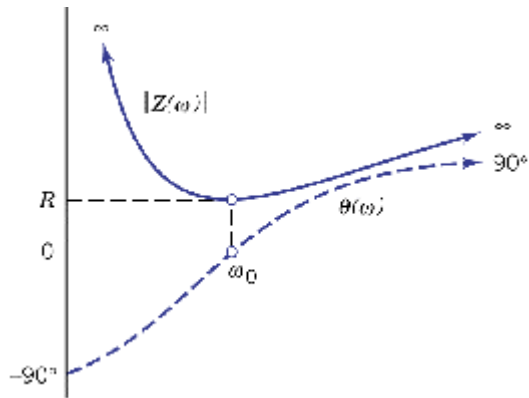
6. Series RLC resonator



$$Z(j\omega) = R + j\omega L + \frac{1}{j\omega C}$$

$$= R + \frac{-\omega^2 LC + 1}{j\omega C}, \omega_o \equiv \frac{1}{\sqrt{LC}}$$

$$X(\omega_o) = 0, Z(\omega_o) = R$$



$$H_{bp}(s) \equiv \frac{V_{bp}}{V_{in}} = \frac{R}{sL + 1/sC + R}$$

$$= \frac{sRC}{s^2 LC + sRC + 1} = \frac{s \frac{R}{L}}{s^2 + s \frac{R}{L} + \frac{1}{LC}}$$

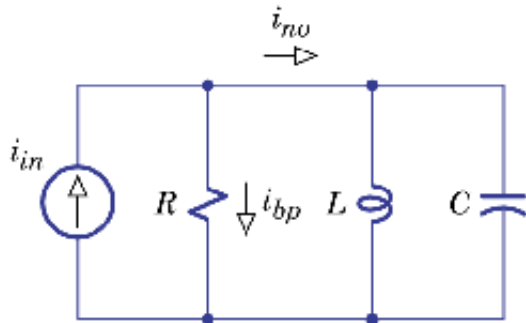
$$= \frac{Ks\omega_o / Q}{s^2 + 2\alpha s + \omega_o^2} = \frac{Ks\omega_o / Q}{(s - p_1)(s - p_2)}$$

$$\omega_o^2 \equiv \frac{1}{LC}, \alpha \equiv \frac{R}{2L}, K = 1$$

$$Q_{ser} \equiv \omega_o \frac{W_L}{P_{loss}} = \omega_o \frac{L}{R} = \frac{\omega_o}{2\alpha}$$

$$p_1, p_2 = -\frac{\omega_o}{2Q} \pm j\omega_o \sqrt{1 - \frac{1}{4Q^2}}$$

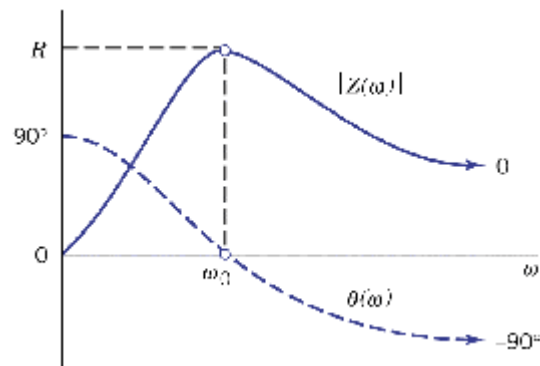
7. Parallel RLC resonator



$$Y(j\omega) = \frac{1}{R} + j\omega C + \frac{1}{j\omega L}$$

$$= \frac{1}{R} + \frac{-\omega^2 LC + 1}{j\omega L}$$

$$B(\omega_o) = 0, Y(\omega_o) = \frac{1}{R}$$



$$H_{bp}(s) = \frac{I_{bp}}{I_{in}} = \frac{1}{R + \frac{1}{sC + 1/sL}}$$

$$= \frac{sL}{s^2 LC + 1} = \frac{sL}{s^2 RLC + sL + R}$$

$$= \frac{s \frac{1}{RC}}{s^2 + s \frac{1}{RC} + \frac{1}{LC}} = \frac{Ks\omega_o / Q}{s^2 + 2\alpha s + \omega_o^2}$$

$$\omega_o^2 = \frac{1}{LC}, \alpha \equiv \frac{1}{2RC}, K = 1$$

$$Q_{par} \equiv \omega_o \frac{W_C}{P_{loss}} = \omega_o RC = \frac{\omega_o}{2\alpha}$$

8. Second-order BPF

$$H_{bp}(s) = \frac{K(w_o / Q)s}{s^2 + (w_o / Q)s + w_o^2}$$

$$H_{bp}(j\omega) = \frac{K(w_o / Q)j\omega}{-w^2 + (w_o / Q)j\omega + w_o^2} = \frac{K}{1 + jQ(\frac{\omega}{w_o} - \frac{w_o}{\omega})}$$

$$a_{bp}(\omega) = \frac{K}{\sqrt{1 + Q^2(\frac{\omega}{w_o} - \frac{w_o}{\omega})^2}}, \theta_{bp} = -\tan^{-1} Q(\frac{\omega}{w_o} - \frac{w_o}{\omega})$$

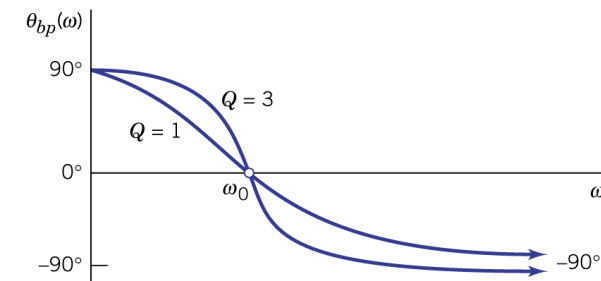
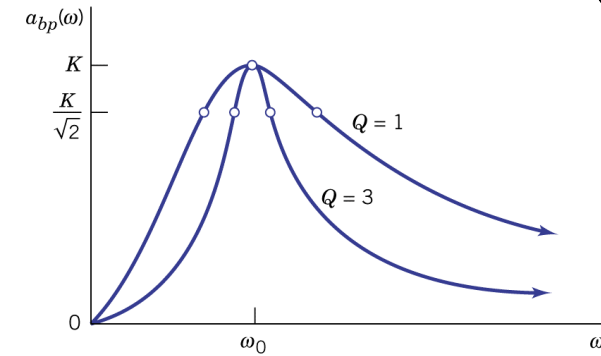
K : midband gain, w_o : center frequency

$$a_{bp}(w_l) = a_{bp}(w_u) \equiv \frac{K}{\sqrt{2}} \rightarrow w_u, w_l = w_o \sqrt{1 + \frac{1}{4Q^2}} \pm \frac{w_o}{2Q}$$

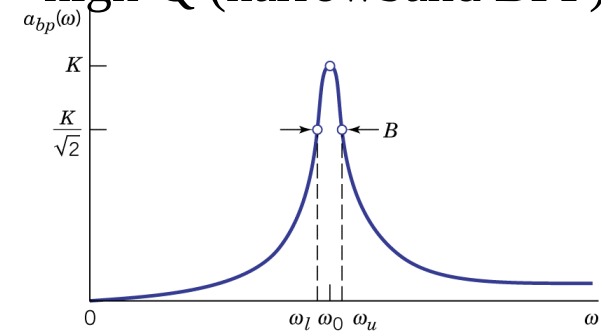
$$\rightarrow B \equiv w_u - w_l = \frac{w_o}{Q}, w_u w_l = w_o^2$$

$Q \geq 10$

$$\rightarrow w_u, w_l \approx w_o \pm \frac{w_o}{2Q}$$



high-Q (narrowband BPF)



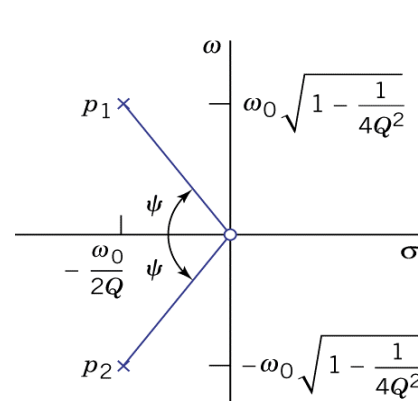
$$H_{bp}(s) = \frac{K(\omega_o / Q)s}{s^2 + (\omega_o / Q)s + \omega_o^2} = \frac{K(\omega_o / Q)s}{(s - p_1)(s - p_2)}, Q = \frac{\omega_o}{2\alpha}$$

(1) underdamped case : $Q > \frac{1}{2}$, or $\alpha < \omega_o$

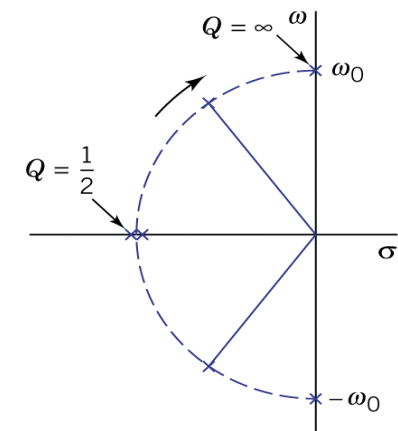
$$p_1, p_2 = -\frac{\omega_o}{2Q} \pm j\omega_o \sqrt{1 - \frac{1}{4Q^2}}, |p_1| = |p_2| = Q,$$

$$\angle p_1 = 180^\circ - \varphi, \angle p_2 = 180^\circ + \varphi, \varphi = \cos^{-1} \frac{1}{2Q}$$

(2) critical damped case : $Q = \frac{1}{2}$



(a) Pole-zero pattern for second-order bandpass filter



(b) Pole movement as Q changes

9. Second-order notch filter

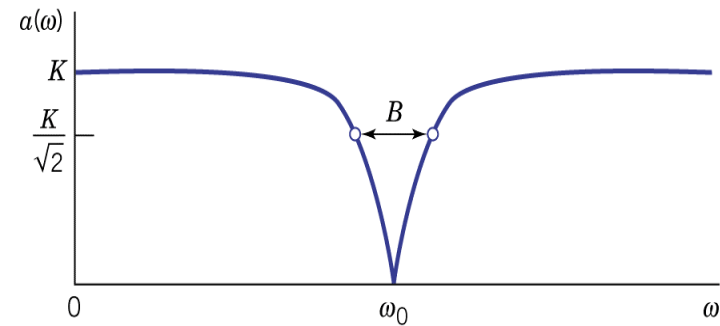
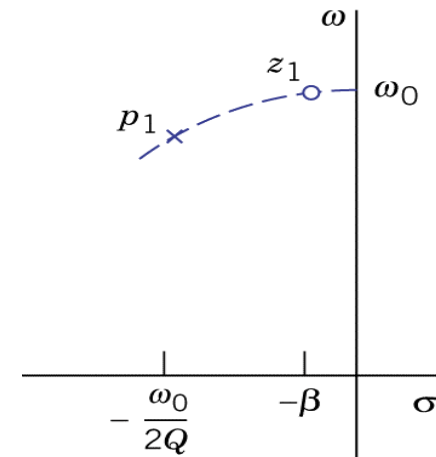
$$H_{no}(s) = \frac{K(s^2 + 2\beta s + w_o^2)}{s^2 + 2\alpha s + w_o^2} = \frac{K(s^2 + 2\beta s + w_o^2)}{s^2 + (w_o/Q)s + w_o^2} = \frac{K(s - z_1)(s - z_2)s}{(s - p_1)(s - p_2)}, \beta \ll \alpha$$

underdamped case: $Q(Q = \frac{w_o}{2\alpha}) > \frac{1}{2}$, or $\alpha < w_o$

$$a_{no}(w_o) = \frac{2KQ\beta}{w_o} \ll K$$

$$p_1, p_2 = -\alpha \pm j\sqrt{w_o^2 - \alpha^2} = -\frac{w_o}{2Q} \pm jw_o\sqrt{1 - \frac{1}{4Q^2}}$$

$$z_1, z_2 = -\beta \pm j\sqrt{w_o^2 - \beta^2} \approx -\beta \pm jw_o$$



10. Ex.11.6 design a parallel BPF to give $\omega_o=20\text{kHz}$, $B=500\text{Hz}$

for a low-loss inductor $R_w \ll \omega L$

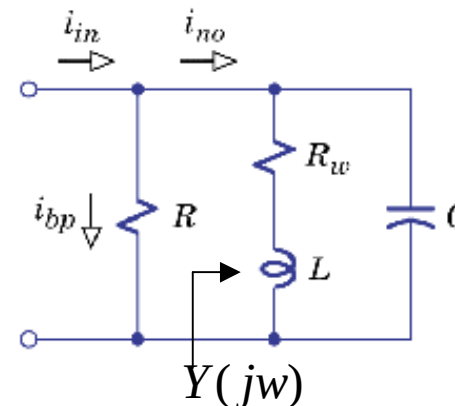
$$Y(j\omega) = j\omega C + \frac{1}{R_w + j\omega L} = \frac{j\omega C R_w - \omega^2 LC + 1}{R_w + j\omega L}$$

$$\approx \frac{C R_w}{L} + j\left(\omega C - \frac{1}{\omega L}\right) = \frac{1}{R_{par}} + j\omega C + \frac{1}{j\omega L}$$

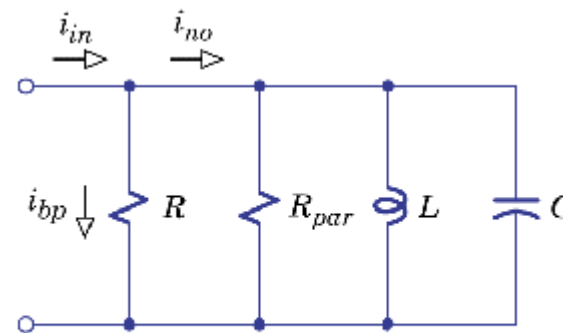
$$\omega_o = \frac{1}{\sqrt{LC}} \rightarrow L = 63.3\text{nF}$$

$$Q = \frac{\omega_o}{B} = 40 = \omega_o (R // R_{par}) C \rightarrow R // R_{par} = 5.03\text{k}$$

$$R_{par} = \frac{L}{C R_w} \rightarrow R_{par} = 13.2\text{k}, R = 8.13\text{k}$$



$$R_w = 1.2\Omega, L = 1\text{mH}$$



(b) Equivalent network for $\omega \approx \omega_o$

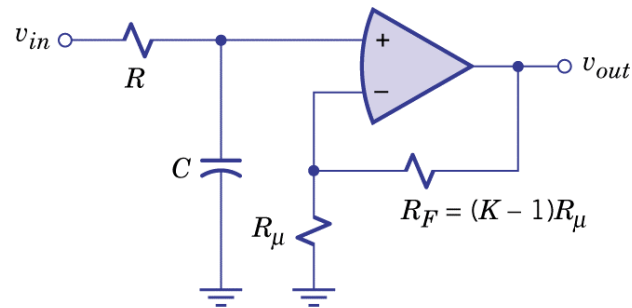
11.3 Op-amp filter circuits

Option

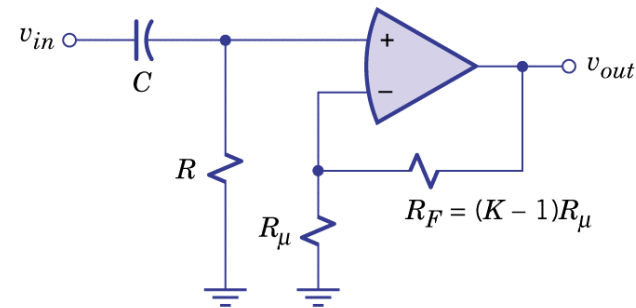
1. Advantages: active filter
2. Noninverting LPF and HPF

- no output loading effects

- $$V_{in} = \frac{R_{\mu}}{R_{\mu} + (K - 1)R_{\mu}} V_{out} \rightarrow V_{out} = KV_{in}$$



(a) Lowpass

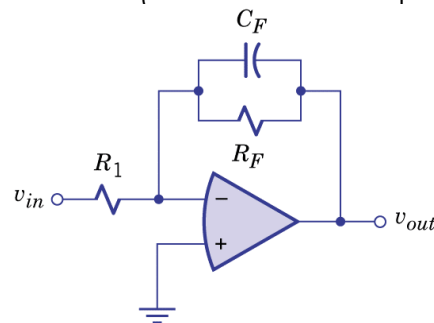


(b) Highpass

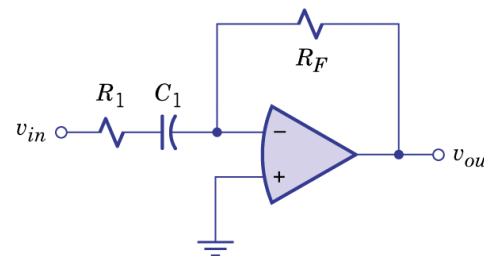
3. Inverting LPF and HPF

- A voltage follower could be inserted as a buffer at the input.
- Network functions

$$H(s) = \frac{V_{out}}{V_{in}} = -\frac{Z_F(s)}{Z_1(s)} \left\{ \begin{array}{l} \text{LPF: } Z_F(s) = \frac{1}{\frac{1}{R_F} + sC_F} = \frac{R_F}{1 + sR_FC_F} = \frac{R_F w_{co}}{s + w_{co}}, w_{co} = \frac{1}{R_FC_F} \\ \rightarrow H(s) = -\frac{R_F}{R_1} \frac{w_{co}}{s + w_{co}} = \frac{K w_{co}}{s + w_{co}}, K = -\frac{R_F}{R_1} \\ \text{HPF: } Z_1(s) = R_1 + \frac{1}{sC_1} = \frac{1 + sR_1C_1}{sC_1} = R_1 \frac{s + w_{co}}{s}, w_{co} = \frac{1}{R_1C_1} \\ \rightarrow H(s) = -\frac{R_F}{R_1} \frac{s}{s + w_{co}} = \frac{Ks}{s + w_{co}}, K = -\frac{R_F}{R_1} \end{array} \right.$$



(a) Lowpass

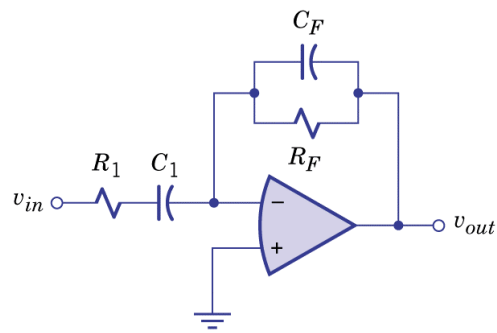


(b) Highpass

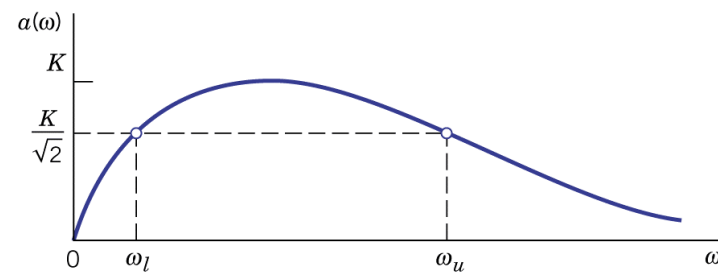
4. Wideband BPF

- Combined LPF and HPF
- Network functions

$$H(s) = -\frac{R_F}{R_1} \frac{s}{s + w_l} \frac{w_u}{s + w_u}, w_l = \frac{1}{R_1 C_1}, w_u = \frac{1}{R_F C_F}, w_l \ll w_u$$



(a) Circuit

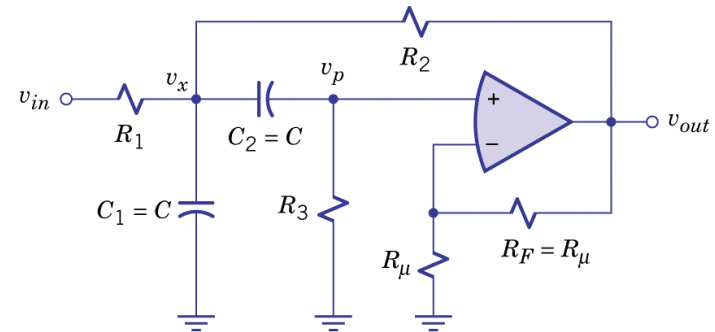


(b) Amplitude ratio

5. Narrowband BPF

- Resonant type BPF to give high Q
- Network functions

$$KCL: \begin{cases} \frac{V_{in} - V_x}{R_1} + \frac{V_{out} - V_x}{R_2} + \frac{V_p - V_x}{1/sC} - \frac{V_x}{1/sC} = 0 \\ \frac{V_x - V_p}{1/sC} - \frac{V_p}{R_3} = 0 \\ \frac{V_x - V_p}{1/sC} \end{cases}$$



$$\Rightarrow H(s) = \frac{V_{out}}{V_{in}} = \begin{cases} K = \frac{2Q}{R_1 C \omega_o} \\ \omega_o = \sqrt{\frac{R_1 + R_2}{R_1 R_2 R_3 C^2}} \\ Q = \frac{R_1 R_2 R_3 C \omega_o}{2R_1 R_2 + R_2 R_3 - R_1 R_3} \end{cases} \rightarrow \begin{cases} R_1 = \frac{2Q}{K \omega_o C} \\ R_2 = \frac{K R_1}{\sqrt{(K-1)^2 + 8Q^2} - 1} \\ R_3 = \frac{K^2 R_1 (R_1 + R_2)}{4Q^2 R_2} \end{cases}$$

- $Q < 0$ for small $R_2 \rightarrow$ oscillation

$$Q = \frac{C \omega_o}{2G_3 + G_1 - G_2}$$

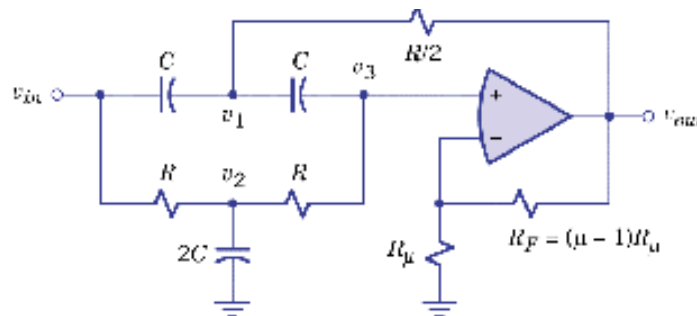
6. Notch filter

- Resonant type BSF to give high Q
- Network functions

$$H(s) = \frac{V_{out}}{V_{in}} = \mu \frac{s^2 + a^2}{s^2 + (4 - 2\mu)as + a^2}, a = \frac{1}{RC}$$

$$= K \frac{s^2 + 2\beta s + w_o^2}{s^2 + (w_o / Q)s + w_o^2}$$

$$K = \mu, \beta = 0, w_o = \frac{1}{RC}, Q = \frac{1}{4 - 2\mu}$$



11.4 Bode plots

Basics

1.dB gain $g(w)dB \equiv 20\log|H(jw)| = 20\log a(w), a(w) = 10^{\frac{g(w)}{20}}$

$$dB \equiv 20\log \frac{V_2}{V_1} = 10\log \frac{P_2}{P_1}$$

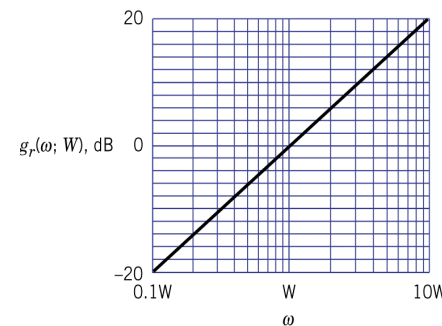
2.Bode plot: plot of $a(w)$ in a log frequency scale

Discussion

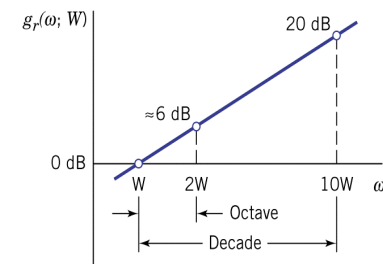
1. Ramp function

$$H_r(s;W) \equiv \frac{s}{W}, H_r(jw;W) \equiv \frac{jw}{W} = \frac{w}{W} \angle 90^\circ$$

$$g_r(w;W) = 20\log \frac{w}{W}, \theta(w;W) = 90^\circ$$



(a)



(b)

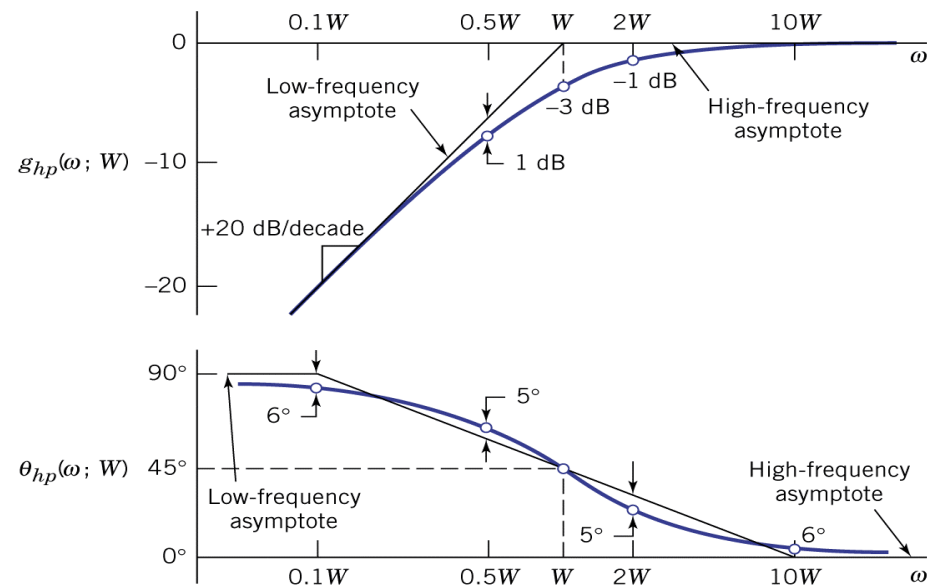
2. Highpass function

$$H_{hp}(s; W) \equiv \frac{s}{s + W}, H_{hp}(j\omega; W) = \frac{j(\omega/W)}{1 + j(\omega/W)}$$

low - frequency : $\omega < 0.1W$, $g_{hp} \approx 20 \log \frac{\omega}{W}$, $\theta_{hp} \approx 90^\circ$

high - frequency : $\omega > 10W$, $g_{hp} \approx 0 \text{ dB}$, $\theta_{hp} \approx 0^\circ$

corner frequency : $\omega = W$, $g_{hp} \approx -3 \text{ dB}$, $\theta_{hp} = 45^\circ$



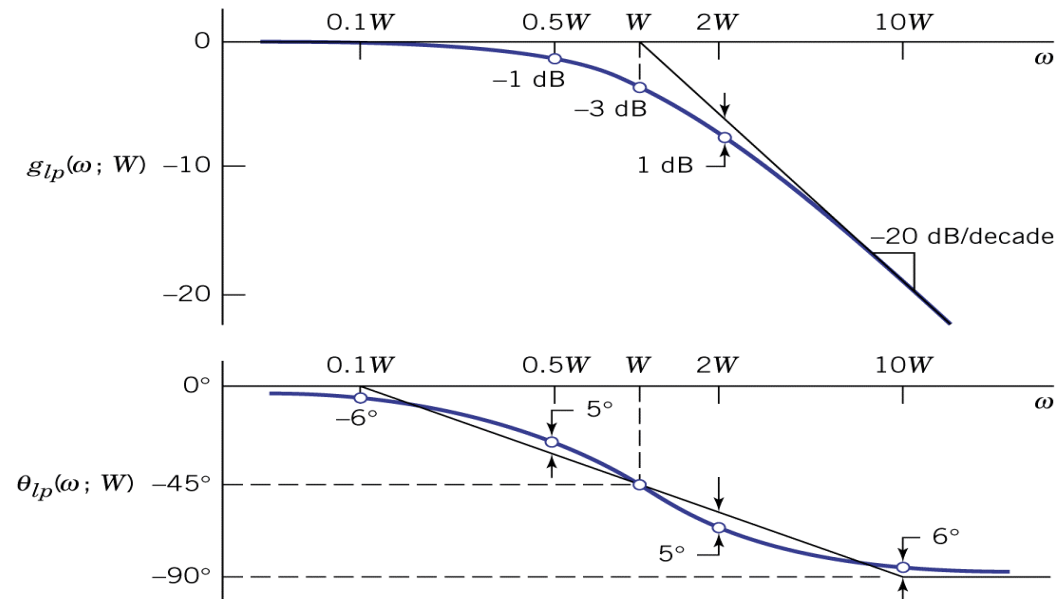
3. Lowpass function

$$H_{lp}(s; W) \equiv \frac{W}{s + W}, H_{lp}(j\omega; W) = \frac{1}{1 + j(\omega/W)}$$

low - frequency : $\omega < 0.1W$, $g_{lp} \approx 0\text{dB}$, $\theta_{lp} \approx 0^\circ$

high - frequency : $\omega > 10W$, $g_{hp} \approx -20 \log \frac{\omega}{W}$, $\theta_{hp} \approx -90^\circ$

corner frequency : $\omega = W$, $g_{hp} \approx -3\text{dB}$, $\theta_{hp} = -45^\circ$



4. Ex.11.8 plot the Bode plot

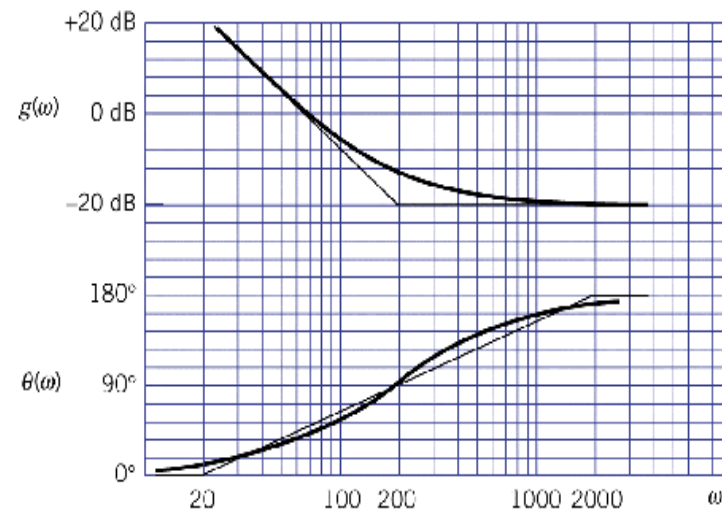
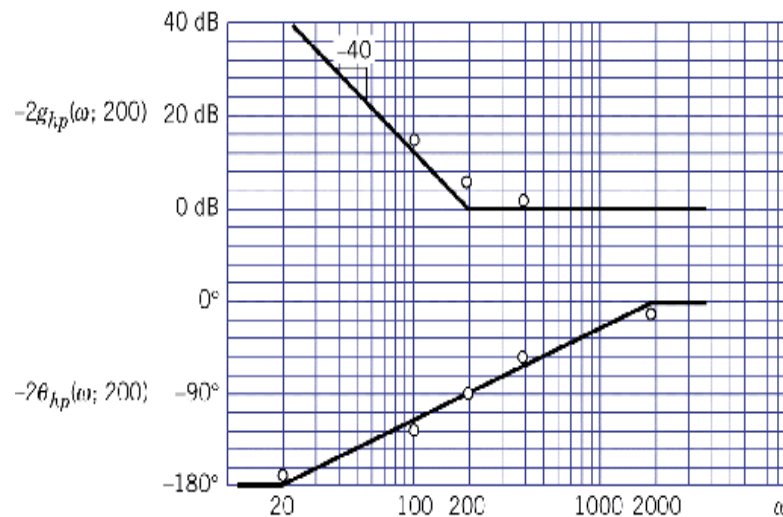
$$H(s) = -\frac{(s+200)^2}{10s^2} = -\frac{1}{10} \left(\frac{s}{s+200} \right)^{-1} = -0.1 H_{hp}^{-2}(s; 200)$$

$$g(w) = -20\text{dB} - 2g_{hp}(w; 200), \theta(w) = 180^\circ - 2\theta_{hp}(w; 200)$$

low - frequency : $w < 20$, $g(w) \approx -20\text{dB} - 40 \log \frac{w}{W}$, $\theta(w) \approx 180^\circ - 2 \times 90^\circ$

high - frequency : $w > 2000$, $g_{hp} \approx -20\text{dB}$, $\theta_{hp} \approx 180^\circ$

corner frequency : $w = W$, $g_{hp} \approx -20\text{dB} - (-6\text{dB})$, $\theta_{hp} = 180^\circ - 2 \times 45^\circ$

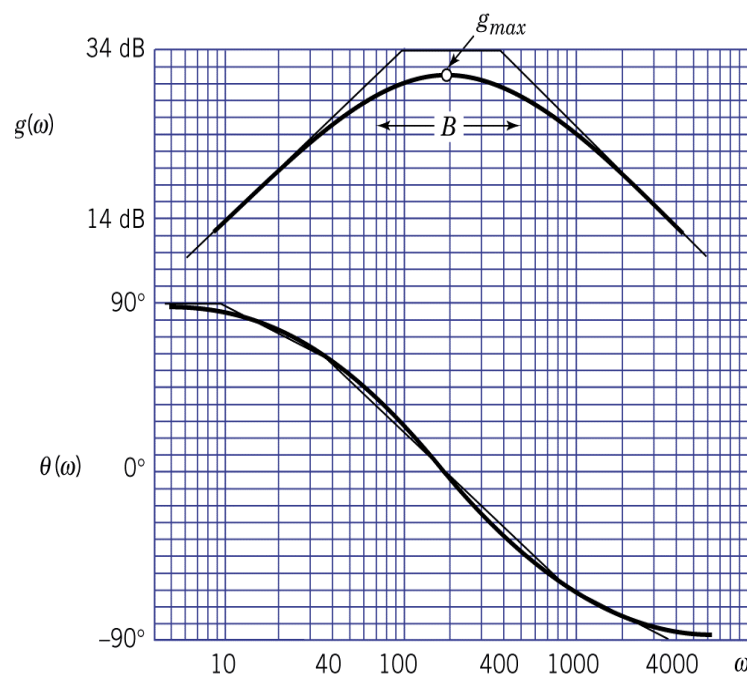
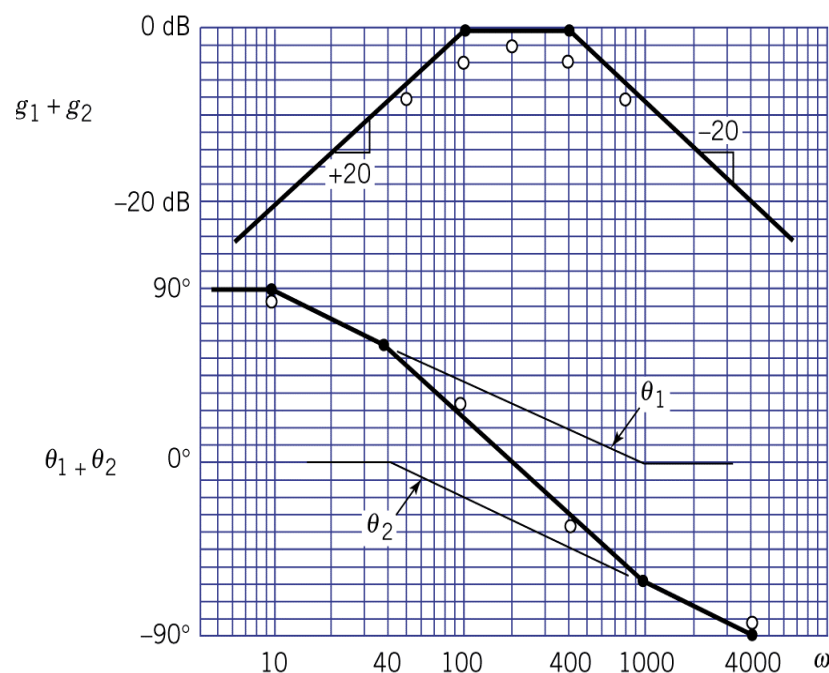


5. Ex.11.9 plot the Bode plot

$$H(s) = \frac{20000s}{(s+100)(s+400)} = 50 \frac{s}{s+100} \frac{400}{s+400} = 50H_{1,hp}(s;100)H_{2,lp}(s;400)$$

$$g(w) = 34\text{dB} + g_{1,hp}(w;100) + g_{2,lp}(w;400), \theta(w) = \theta_{1,lp}(w;100) + \theta_{2,hp}(w;400)$$

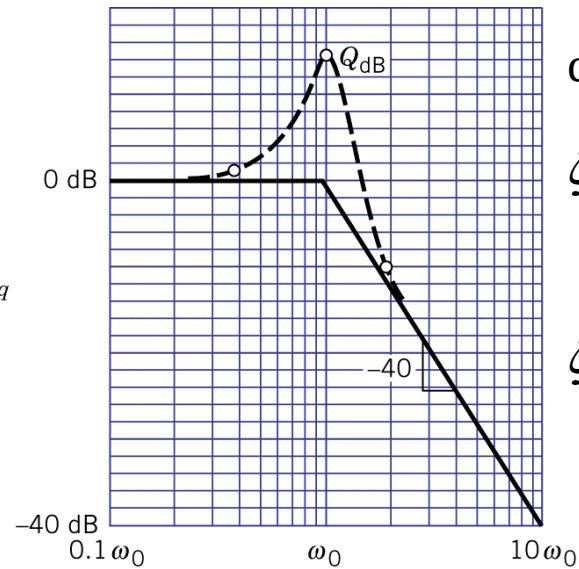
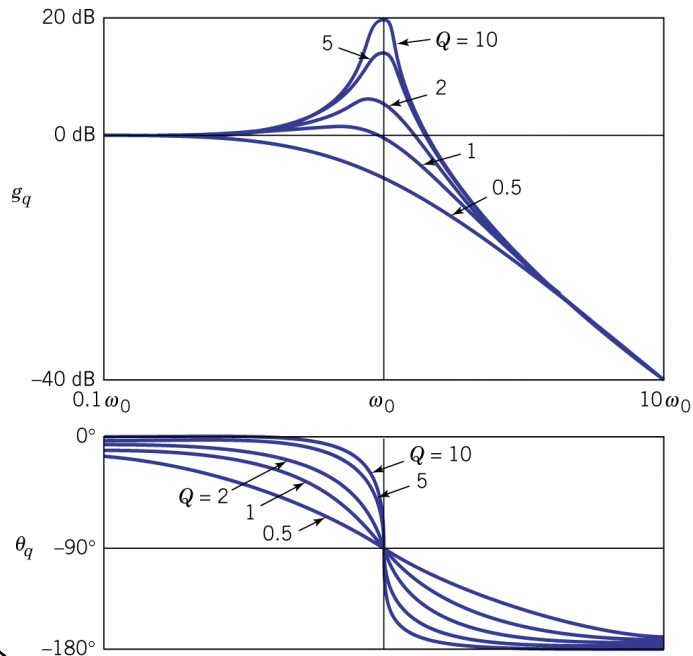
$$w \geq 100, g_{1,hp}(w) \approx 0\text{dB}; w \leq 400, g_{2,lp}(w) \approx 0\text{dB}$$



6. Quadratic function

$$H_q(s; w_o, Q) \equiv \frac{w_o^2}{s^2 + (w_o/Q)s + w_o^2}, H_q(jw; w_o, Q) = \frac{1}{1 - (w/w_o)^2 + j(w/Qw_o)}$$

$$H_q(jw; w_o, Q) \approx \begin{cases} 1, w \ll w_o \\ -(\frac{w_o}{w})^2, w \gg w_o \\ -jQ, w = w_o \end{cases} \rightarrow g_q \approx \begin{cases} 0\text{dB}, w < 0.1w_o \\ -40\log\frac{w}{w_o}, w > 10w_o \\ 20\log Q = Q_{\text{dB}}, w = w_o \end{cases}$$



damping ratio

$$\zeta \equiv \frac{1}{2Q} = \frac{\alpha}{w_o}$$

$$\zeta \begin{cases} < 1, \text{underdamp} \\ = 1, \text{critical damp} \\ > 1, \text{overdamp} \end{cases}$$

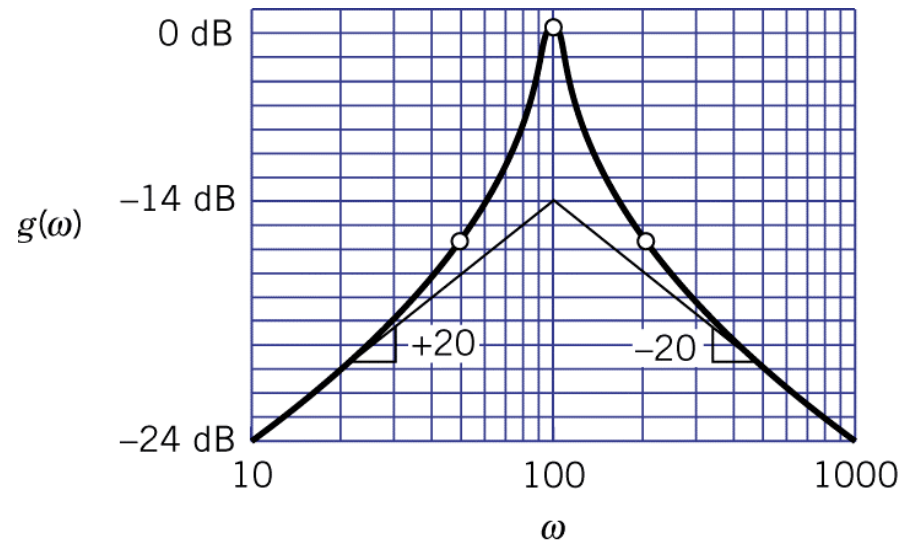
7. Ex.11.10

$$H(s) = \frac{20s}{s^2 + 20s + 10^4} = 0.2 \frac{s}{100} \frac{10^4}{s^2 + 20s + 10^4} = 0.2H_r(s;100)H_q(s;100,5)$$

$$w_o = 100, \frac{w_o}{Q} = 20 \rightarrow Q = 5$$

$$g(w) = -14\text{dB} + g_r(w;100) + g_q(w;100,5)$$

$$w = 100, g(w) = -14 + 0 + 20\log 5 = 0\text{dB}$$

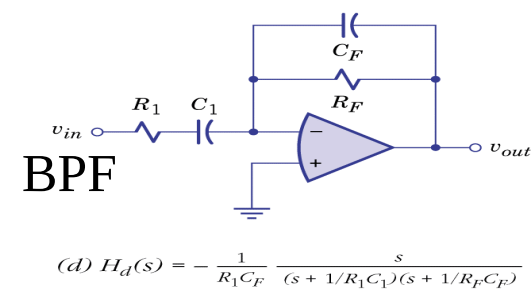
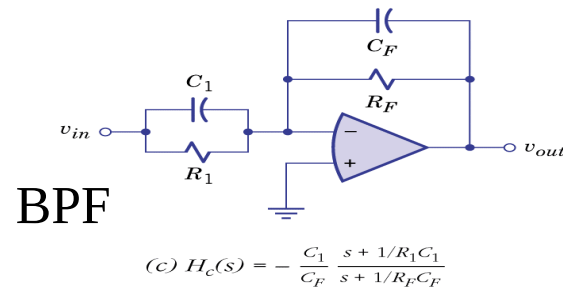
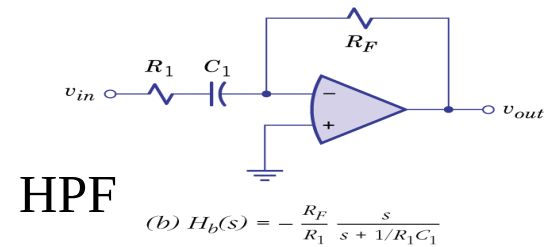
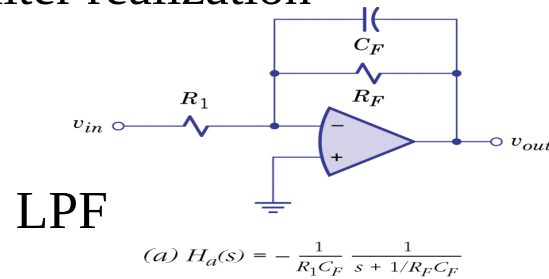


11.5 Frequency-response design

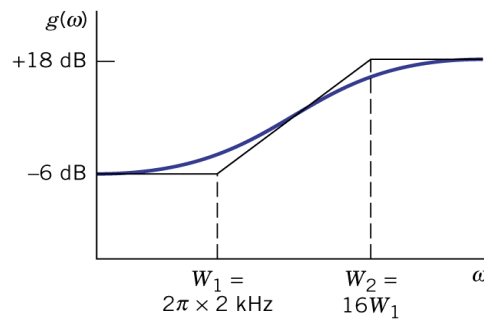
Optional

1. Design the filter from frequency-response and Bode plot

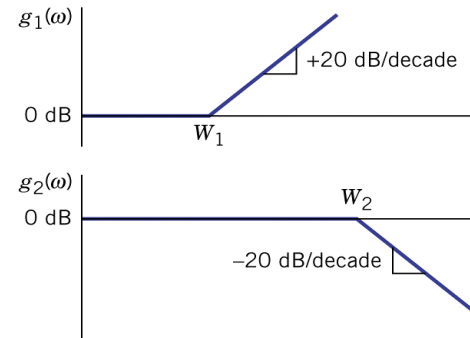
- line slope $m(\pm 20\text{dB/decade})$
- corner frequencies W_1, W_2 , number of decades $= \log \frac{W_2}{W_1}$
- factored frequency-response
 $g(w) = K_{dB} + g_1(w) + g_2(w) + \dots \rightarrow H(s) = \pm |K| H_1(s) H_2(s) \dots$
- filter realization



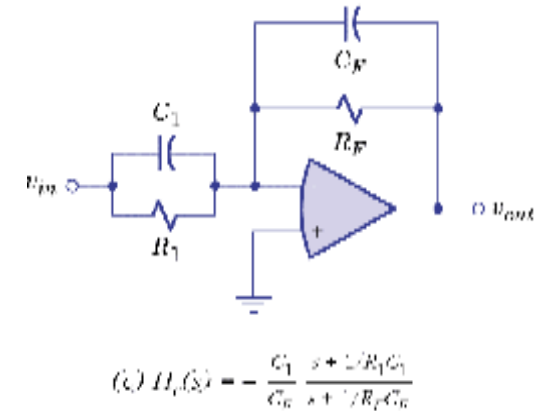
2. Design a FM pre-emphasis circuit



(a) Gain curve for FM preemphasis



(b) Asymptotic plots



$$\text{slope} = \frac{24\text{dB}}{\log \frac{16W_1}{W_1}} = \frac{24\text{dB}}{1.2\text{decades}} = 20\text{dB/decade}$$

$$g(\omega) = K_{dB} + g_1(\omega) + g_2(\omega), K_{dB} = -6\text{dB}, g_1(\omega) = g_{lp}^{-1}(\omega; W_1), g_2(\omega) = g_{lp}(\omega; W_2)$$

$$H(s) = 0.5 \frac{s+12600}{12600} \frac{20100}{s+20100} = 8 \frac{s+12600}{s+20100}$$

$$\rightarrow \frac{C_1}{C_F} = 8, \frac{1}{R_1 C_1} = 12600, \frac{1}{R_F C_F} = 20100$$

$$\text{take } R_F = 10\text{k}\Omega \rightarrow C_F = 0.5\text{nF}, C_1 = 4\text{nF}, R_1 = 20\text{k}\Omega$$

11.6 Butterworth filters

Optional

1. Butterworth polynomial

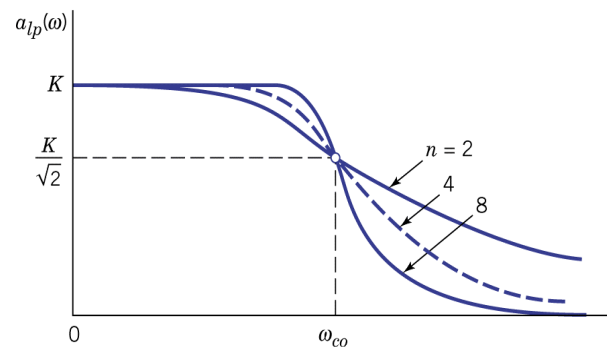
$$|B_n(j\omega)| = \sqrt{\omega^{2n} + \omega_{co}^{2n}}, \frac{d^m}{d\omega^m} |B_n(j\omega)| \Big|_{\omega=0} = 0, m = 1, 2, \dots, 2n-1$$

$$|B_n(j\omega)| \approx \begin{cases} \omega_{co}^n, & \omega < \omega_{co} \\ \omega^n, & \omega > \omega_{co} \end{cases}$$

2. n-th order LPF

$$H_{lp}(s) = \frac{K\omega_{co}^n}{\sqrt{s^{2n} + \omega_{co}^{2n}}}, H_{lp}(j\omega) = \frac{K\omega_{co}^n}{\sqrt{\omega^{2n} + \omega_{co}^{2n}}} = \frac{K}{\sqrt{1 + \left(\frac{\omega}{\omega_{co}}\right)^{2n}}}$$

$$a_{lp}(\omega) = \frac{K}{\sqrt{1 + \left(\frac{\omega}{\omega_{co}}\right)^{2n}}} \left\{ \begin{array}{l} \approx K, \omega < \omega_{co} \\ \approx \left(\frac{\omega_{co}}{\omega}\right)^n K \ll K, \omega > \omega_{co} \\ = \frac{K}{\sqrt{2}}, \omega = \omega_{co} \end{array} \right.$$

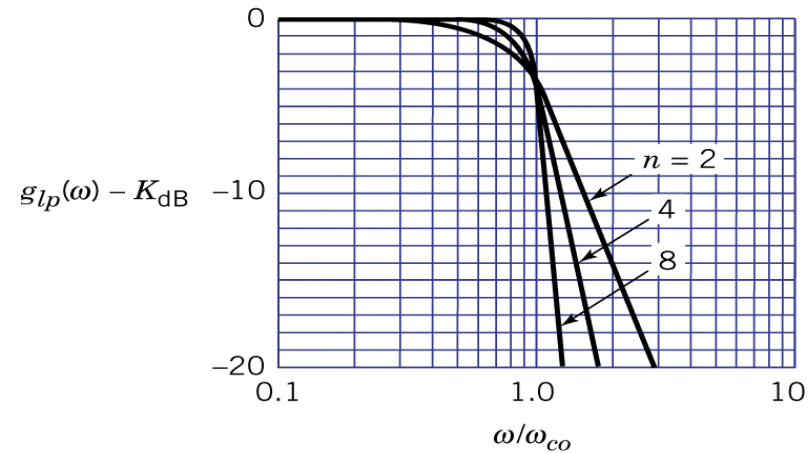


3. Bode plot

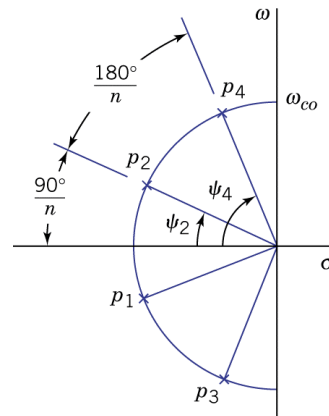
$$g_{lp}(\omega) = 20 \log a_{lp}(\omega)$$

maximal flatness response

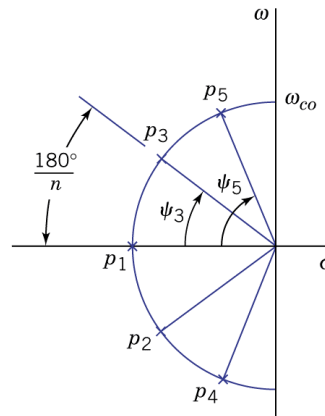
slope : $20n \text{ dB/decade}$



4. Poles are uniformly spaced by angles $180^\circ/n$ around a semicircle of radius ω_{co} in the left half of s-plane.



(a) Even n



(b) Odd n

5. Ex.11.12 Design a Butterworth LPF to give $f_{co}=15\text{kHz}$, $a_{lp}(w) \leq K/8$ for $f \geq 23\text{kHz}$

$$a_{lp}^2(w) = \frac{K^2}{1 + \left(\frac{w}{w_{co}}\right)^{2n}} \leq \frac{K^2}{8^2}, w \geq 2\pi \times 23k \rightarrow \frac{K^2}{1 + \left(\frac{23}{15}\right)^{2n}} \leq \frac{K^2}{8^2} \rightarrow n \geq 4.85, n = 5$$

6. n-th order HPF

$$H_{hp}(s) = \frac{Ks^n}{\sqrt{s^{2n} + w_{co}^{2n}}}, a_{lp}(w) = \frac{K}{\sqrt{1 + \left(\frac{w_{co}}{w}\right)^{2n}}}$$

